

# Evaluating C-ITS

TrafficQuest-TRAIL-TU Delft Seminar 13 Sep 2016  
"New Developments in Evaluating ITS"

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Research School for Transport,  
Infrastructure and Logistics



**TrafficQuest**

CENTER FOR EXPERTISE ON TRAFFIC MANAGEMENT





(Real-time) diagnostics,  
estimation & prediction



Evaluation &  
assessment



(Open-source)  
Multiscale Simulation



Smart Urban Regions of the Future  
(SURF)



(BIG) Data  
Processing



Virtual Reality,  
Gaming



SETA

HORIZON 2020

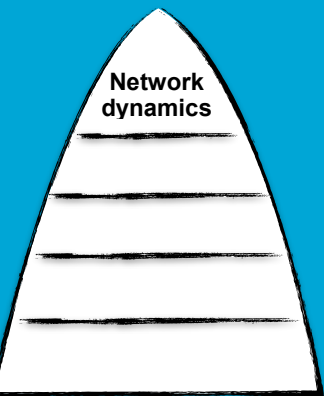
Mixed Reality

5 PhDs  
2 PD + Programmer  
Many external collaborators  
Many proposals "hanging"

# Today's talk

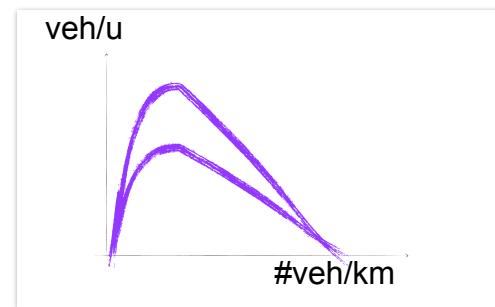
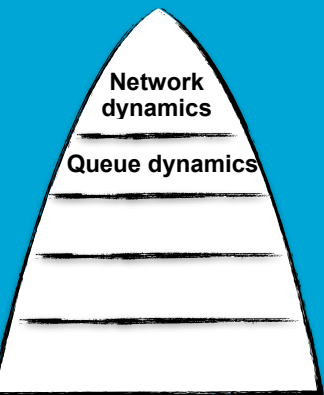
- Motivation
- A cyclic approach to evaluating C-ITS
- Tools for evaluation:
  - Smart ways to access traffic data
  - SimSmartMobility

# Motivation



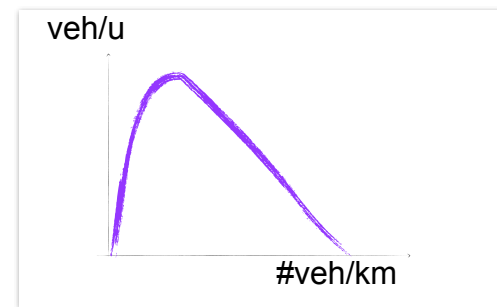
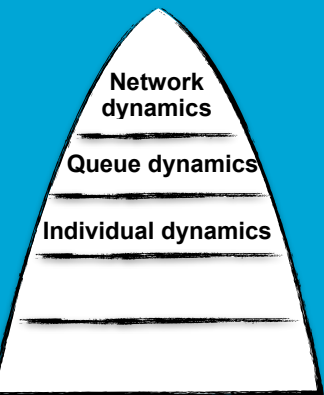
Effect C-ITS and AD in networks?

# Motivation



Effect C-ITS and AD on bottleneck capacity?

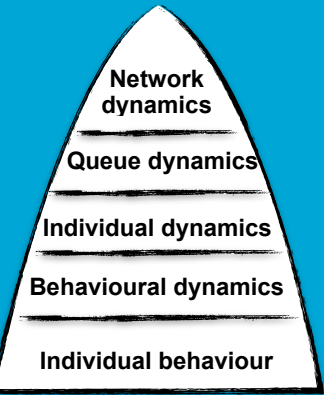
# Motivation



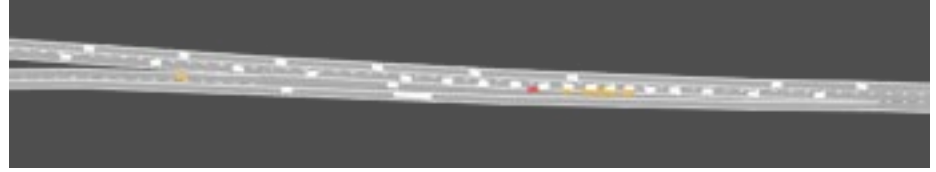
Idealised (automated)  
drivers: longitudinal  
behaviour surprisingly  
good (lateral not so)

Effect C-ITS and AD on vehicle interactions?

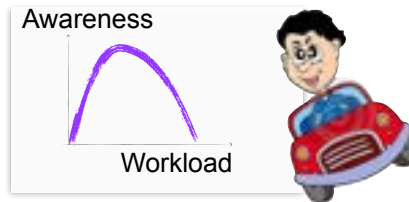




Idealised (automated) drivers: longitudinal behaviour surprisingly good (lateral not so)



## Quantitative models to simulate individual behaviour under C-ITS/AR and predict the emergent interactions



Traffic psychology & Human Factors: **qualitative** theories and **conceptual** models for (individual) driving behaviour

# Fundamental problems of evaluating Cooperative ITS and Vehicle Automation

- Drivers WITH “intelligent vehicles” will behave differently (e.g. transition from driving to monitoring)
- Drivers WITHOUT such technology will behave differently when interacting with these intelligent vehicles

“... not too fast! Mind the cyclist... LEFT here...brake... BRAKE YOU FOOL! ... Careful there's a dog ...”



<http://www.lawandai.com/2016/05/15/nhtsa-and-autonomous-vehicles-part-2/>



# Fundamental problems of evaluating Cooperative ITS and Vehicle Automation

- Drivers WITH “intelligent vehicles” will behave differently (e.g. transition from driving to monitoring)
- Drivers WITHOUT such technology will behave differently when interacting with these intelligent vehicles

Evidence from:

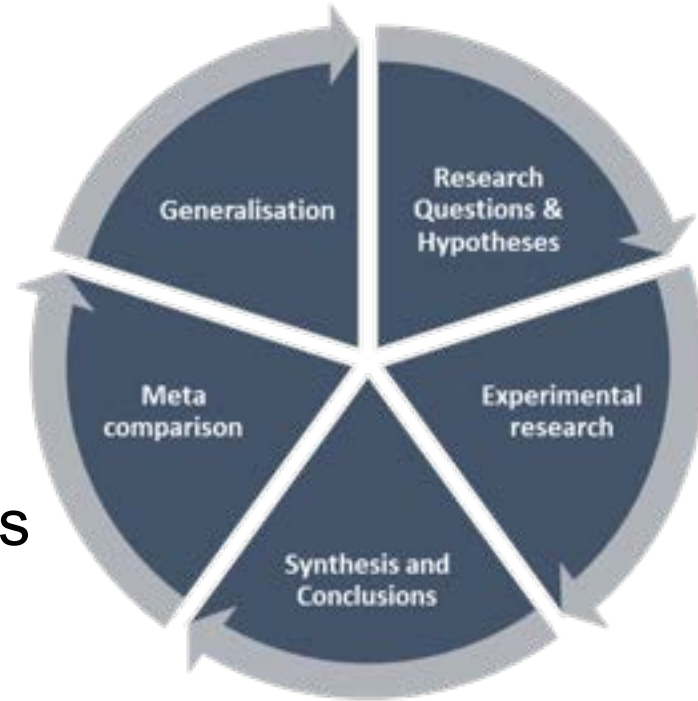
- Field-tests: high costs, small sample and limited scenarios
- Driving simulator: validity / generalisation

Evidence from:

- Driving simulator (& field-tests?)
- Multi-scale simulation: constraints on what can happen on average

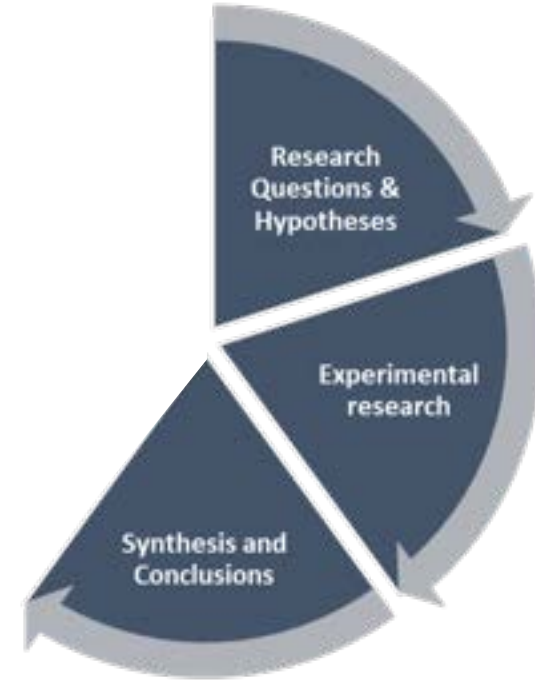
# The C-ITS Evaluation Cycle

- Product of the ITS-Effects round-table
- Adds two crucial ingredients:
  - Meta comparing and generalisation of results
  - Cyclic thinking: simulation in the development loop



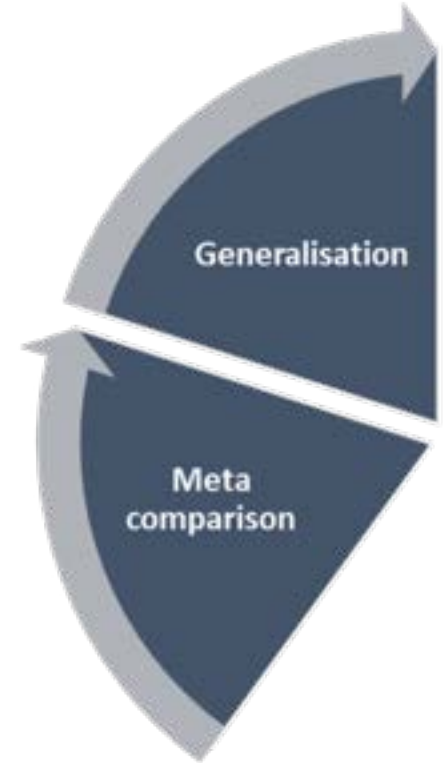
# The C-ITS Evaluation Cycle

- Step 1-3
  - Driving sim research, Field-tests & Pilots
  - Use existing methodologies (e.g. FESTA)
  - Increase rigor in exp. design and hypothesis testing



# The C-ITS Evaluation Cycle

- Meta comparison & generalisation
  - International comparison results field tests / pilots
  - Simulation in the loop: what if ? (higher penetration, geo distribution, ... )
  - Simulation = re-design & incubator new hypotheses



# Today's talk

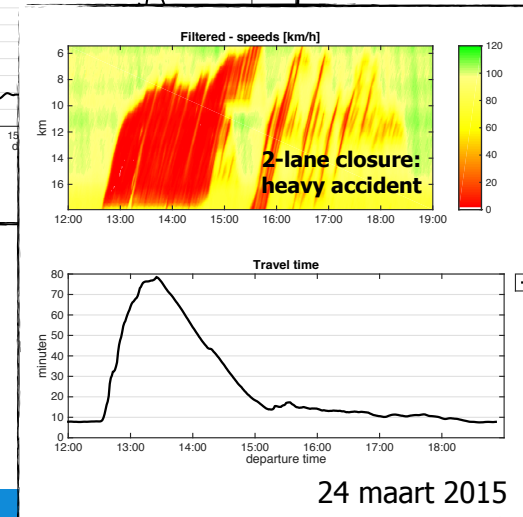
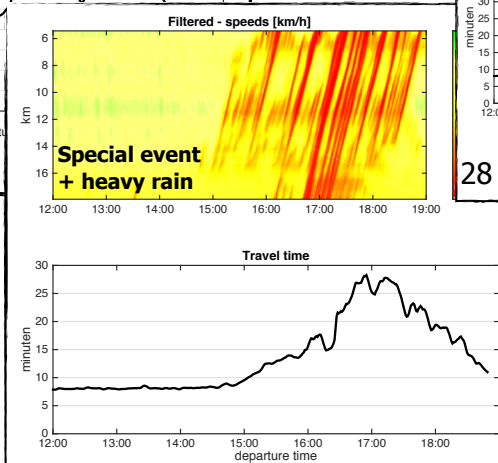
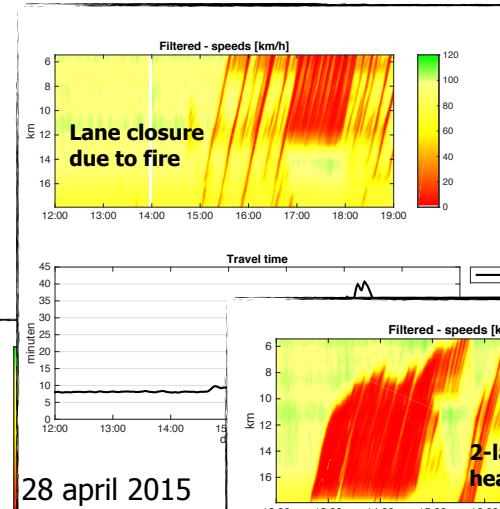
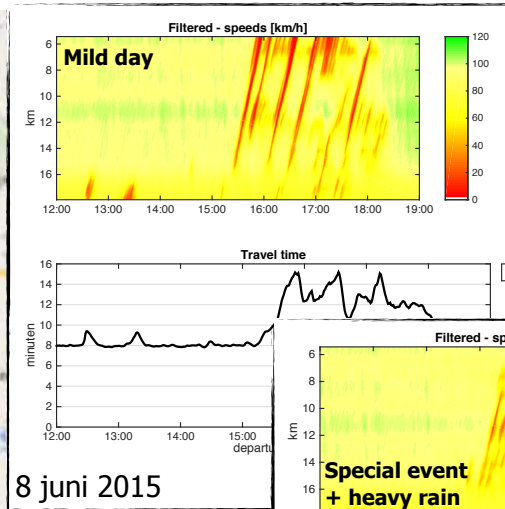
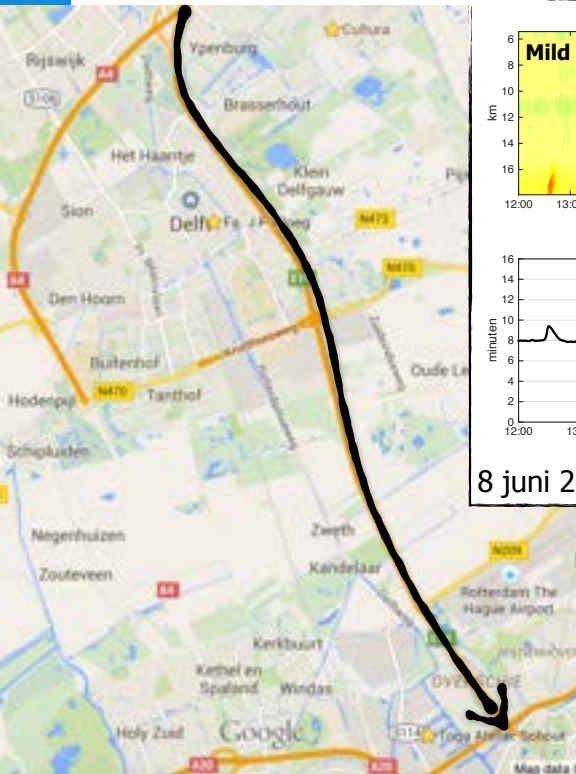
- Motivation
- A cyclic approach to evaluating C-ITS
- Tools for evaluation:
  - Smart ways to access traffic data
  - SimSmartMobility

# Traffic observatory

- The overall plan:
  - Phase 1: COSI: make the historical database of NDW “intelligent” so you can search for information
  - Phase 2: Develop multi scale traffic state estimators
  - Phase 3: Develop Multi-scale demand estimators
  - Phase 4: Develop simulation and prediction capabilities
- Phase 2-3 (+ bit of 4): STW proposal MiRRORS (still) under review

# Selecting data for simulation studies tough

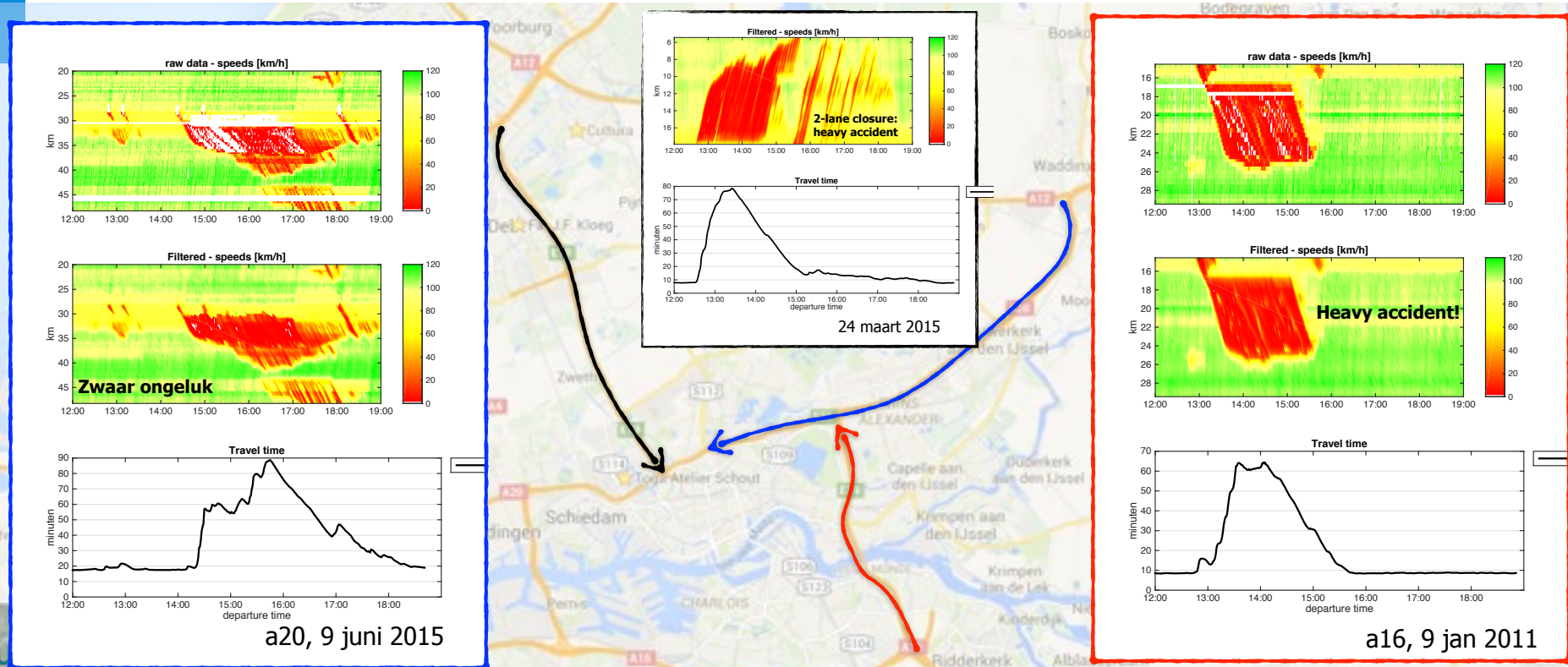
Limited search options supposes you know where and when you want to look





# An intelligent historical database

Fast search one abstraction level higher: traffic patterns and meta data





# Classification method 1: using image features

## Manually classify traffic situations to similar categories

### (available) Metadata

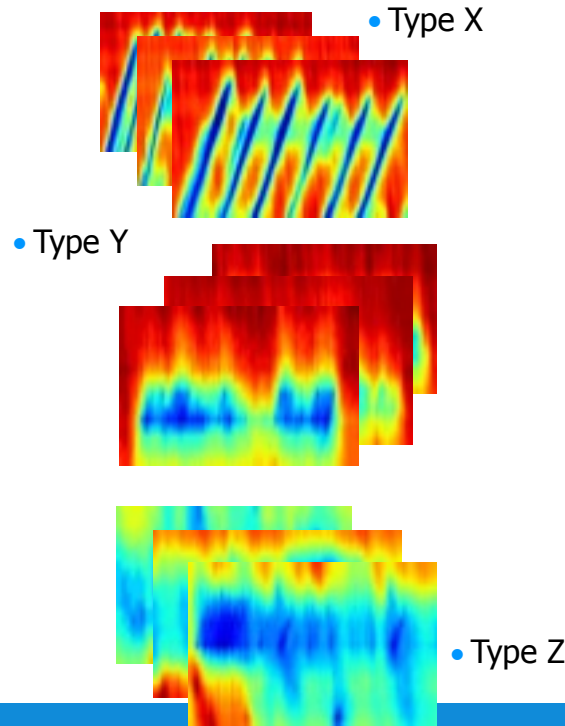
#### from databases / GIS:

- Date & time
- Geo & digraph info
- Weather
- Incidents / events
- etc

#### based on dynamic data

- Vehicle loss hours
- Travel time distribution
- data quality
- % trucks
- demand patterns
- etc

### clustered congestion images



These images may have

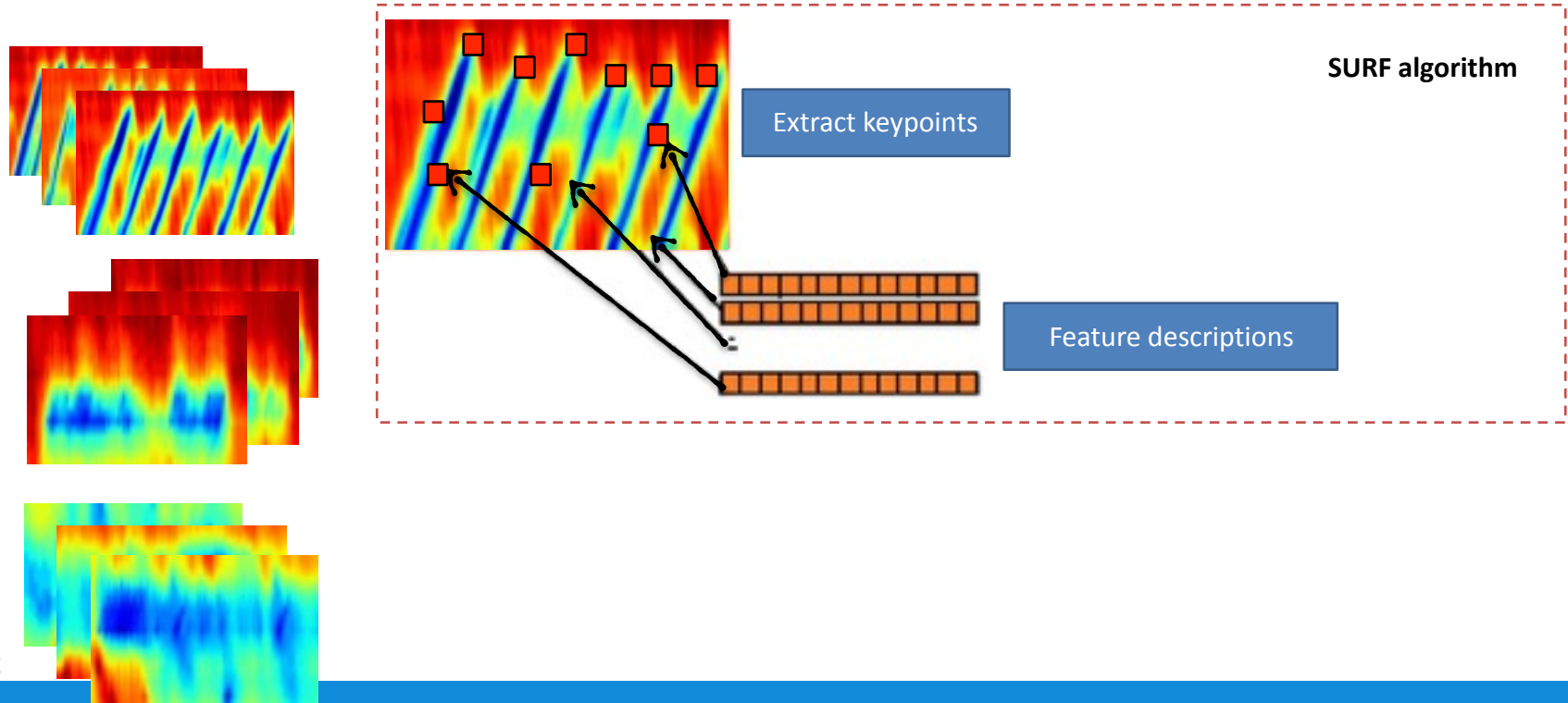
- different sizes
- different resolutions
- different wxh ratios

they must have

- similar colormaps
- similar ratio time/space  
(shockwave speeds)

# Classification method 1: using image features

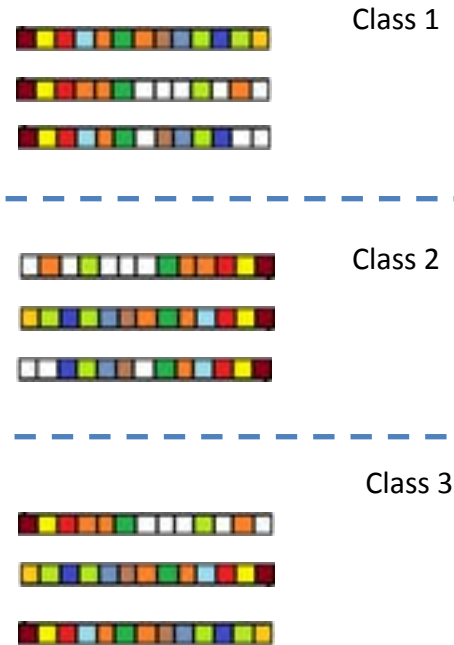
Decompose patterns in a “bag of features” (around so-called keypoints)



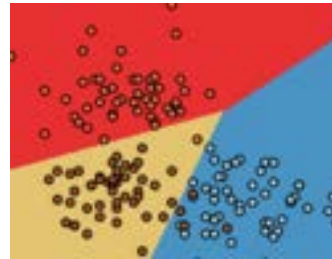
# Classification method 1: using image features

**Construct histograms of what's in these bags to train an SVM classifier ...**

Feature vectors



SVM



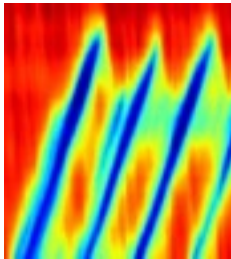
Save

Pattern recognition  
model

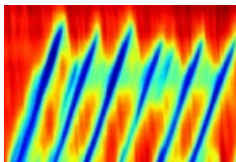
# Classification method 1: using image features

... that can be used to classify unseen patterns

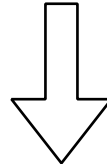
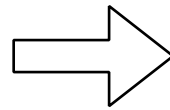
Unknown pattern



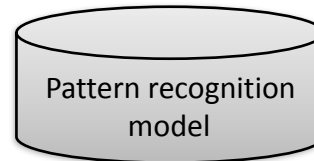
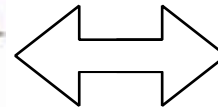
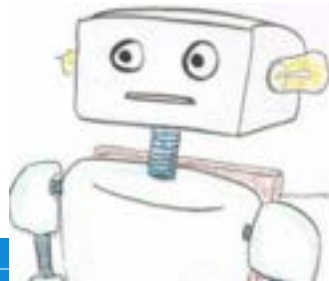
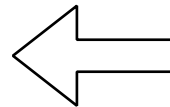
Pattern Type X



unravel in "features"



Classify



Iterative process

1. Manual (re) classification
2. Training
3. Testing
4. Back to 1 until satisfied

# Classification method 2: using base shapes

## Manually classify traffic situations to similar categories

### (available) Metadata

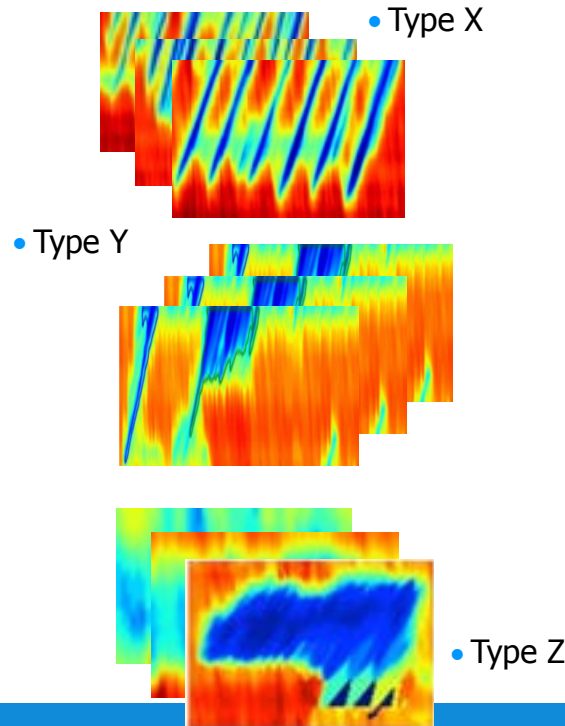
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### clustered congestion images

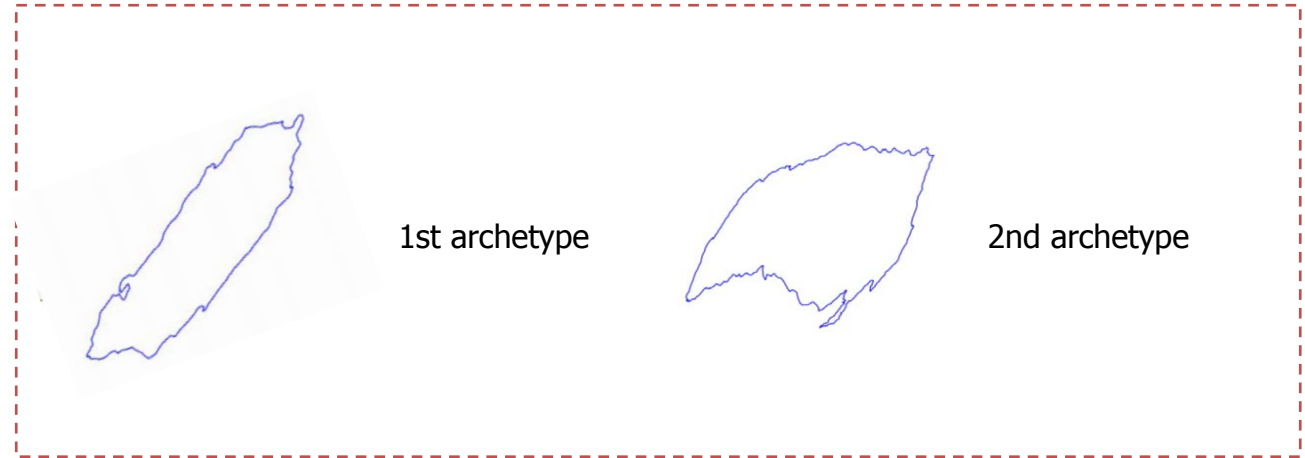
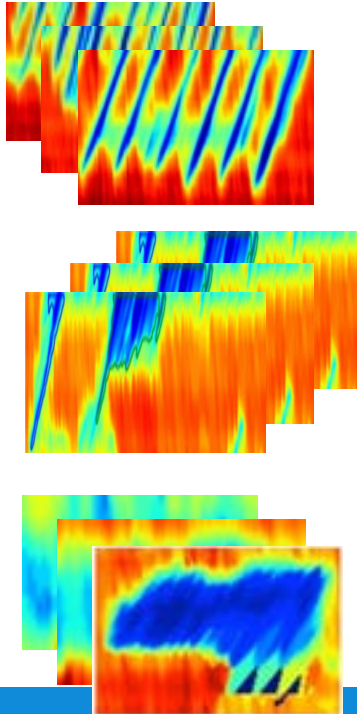


These images have

- common recurring archetypes/shapes
- different sizes

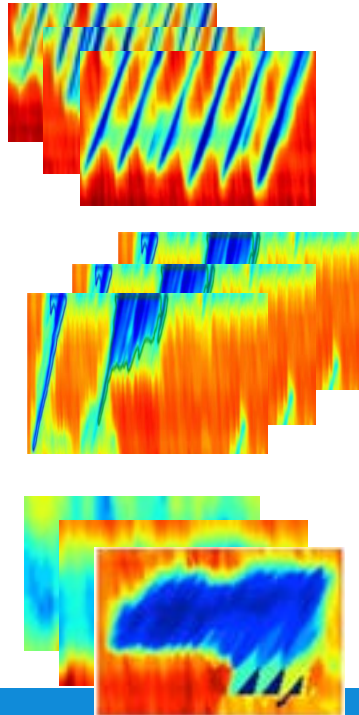
# Classification method 2: using base shapes

**Identify distinct archetypes/shapes from the patterns  
(another way of mimicking how humans recognise faces)**

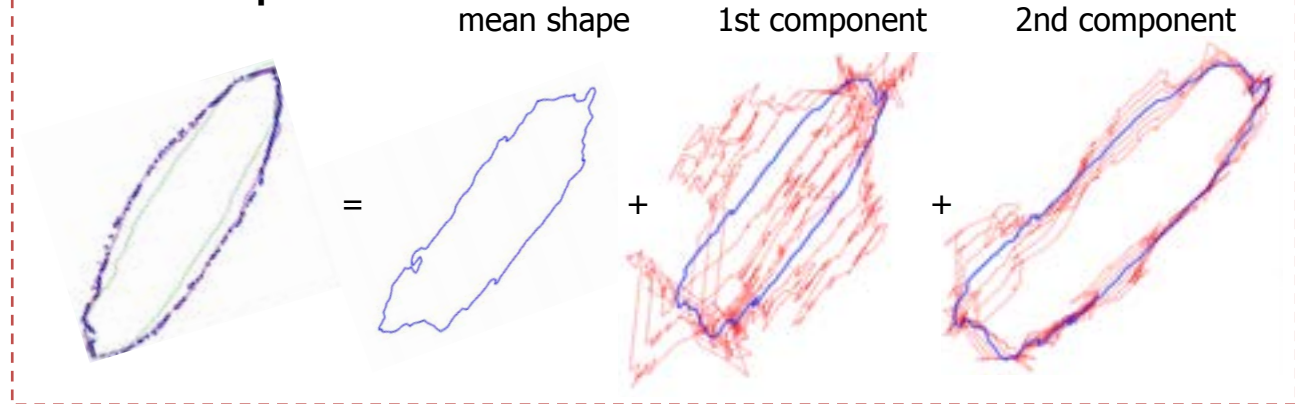


# Classification method 2: using base shapes

**Figure out possible variations around these base shapes**

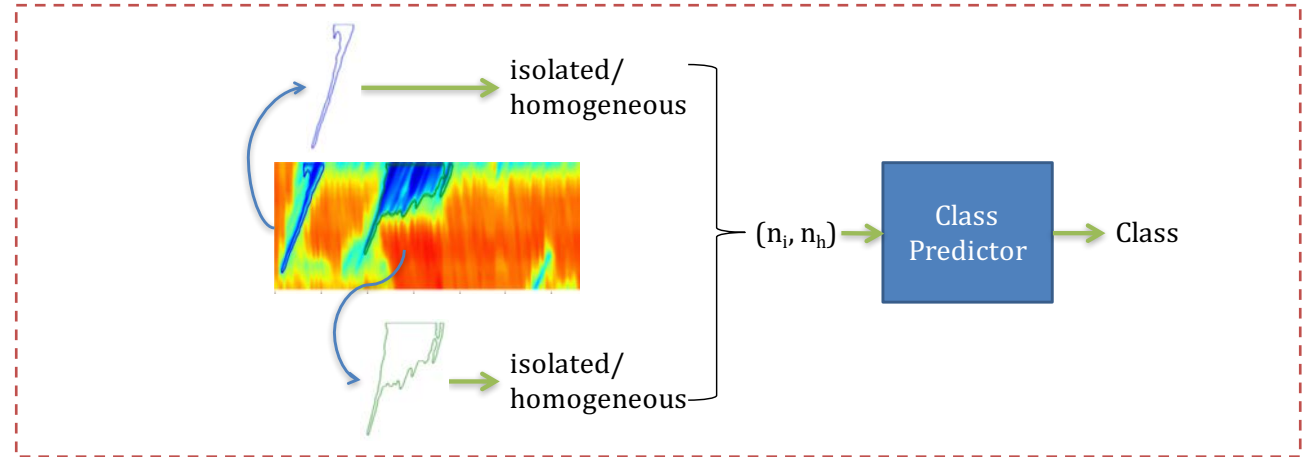
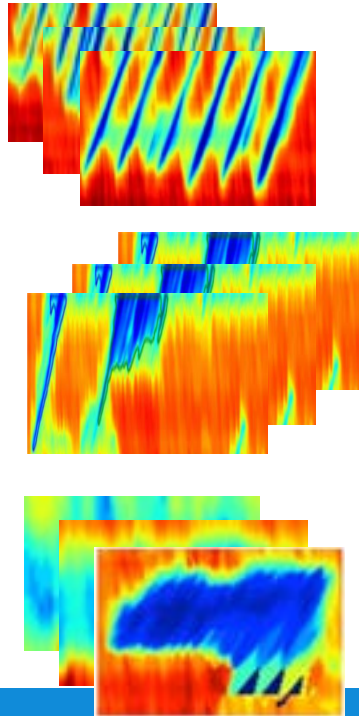


## Statistical Shape Model



# Classification method 2: using base shapes

**Construct histogram of base shapes in images to train a classifier ...**





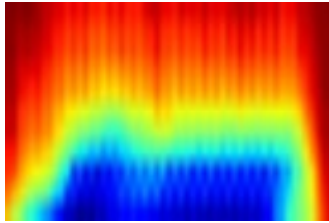
# Superfast searching through traffic patterns

... that can be used to classify unseen patterns

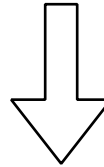
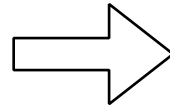
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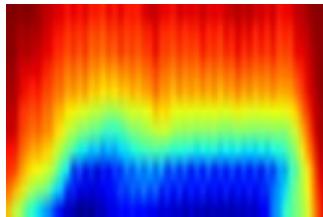
Unknown pattern



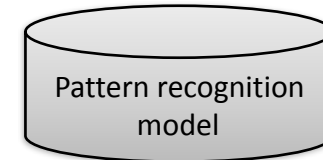
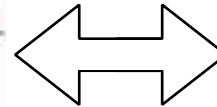
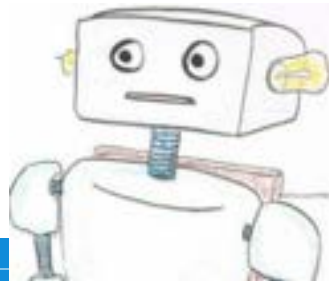
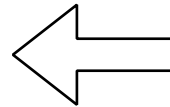
2D feature vector,  $(n_i, n_h)$



Pattern Type X



Classify



Demo

# Today's talk

- Motivation
- A cyclic approach to evaluating C-ITS
- Tools for evaluation:
  - Smart ways to access traffic data
  - **SimSmartMobility**

# SimSmartMobility

- Simulation toolkit to evaluate C-ITS (Smart Mobility)
- Key developments:
  - HLA compliant (but max faster/scalable) event-based sim architecture (IMB)
  - DSOL/OpenTrafficSim multi-scale (and in time multi-modal) simulation framework
  - Standardisation interfaces to model input, output and real-time state
- Three use cases (end of 2016)
  - 2 Urban: GLOSA and Traffic Control Optimisation
  - 1 Freeway: controlling wide moving jams

We are in it for the long term:

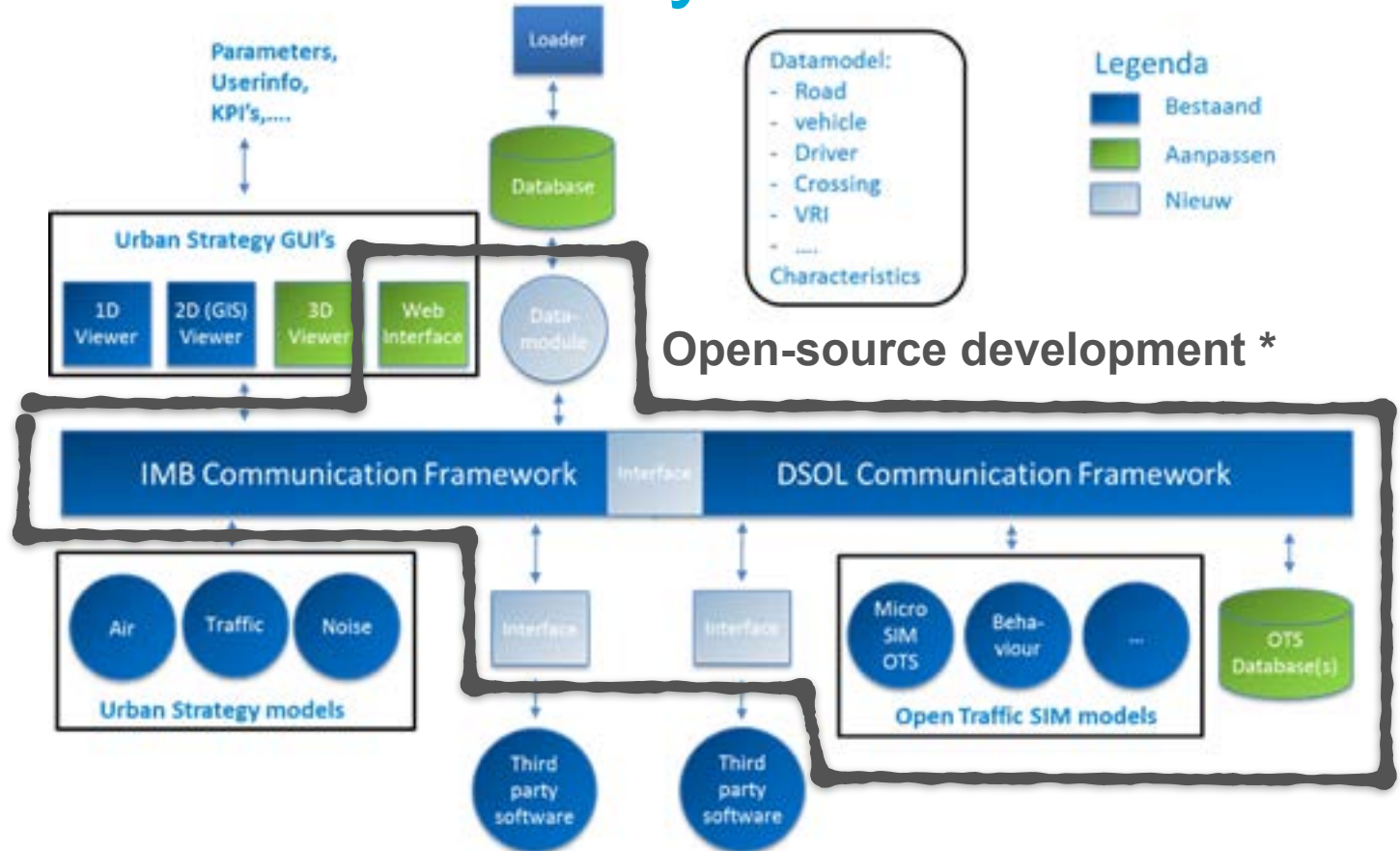
- Period 2016-2019
- Collaboration Research institutes, Market & Public authorities
- 

Connecting  
Mobility

**TNO** innovation  
for life

 **TU Delft**

# SimSmartMobility



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**Thanks!**

