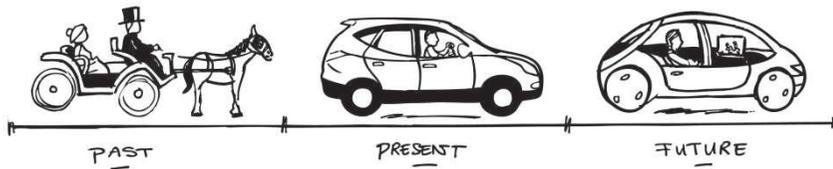




Rijkswaterstaat  
*Ministerie van Infrastructuur en Milieu*



# Past, Present & Future

Frans op de Beek  
Principal advisor trafficmanagement  
Rijkswaterstaat

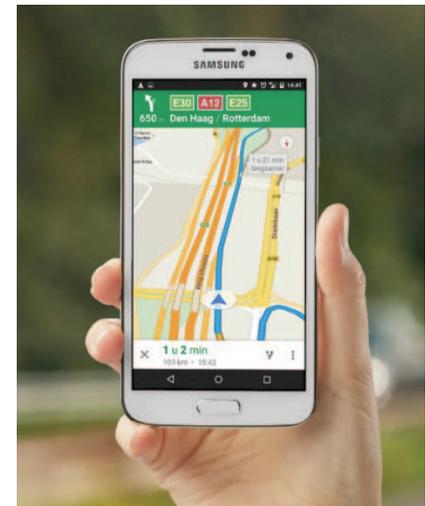


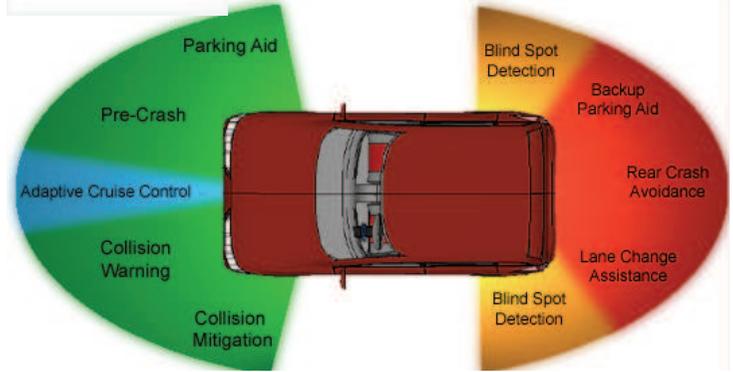
First traffic jam in NL 29-05-1955

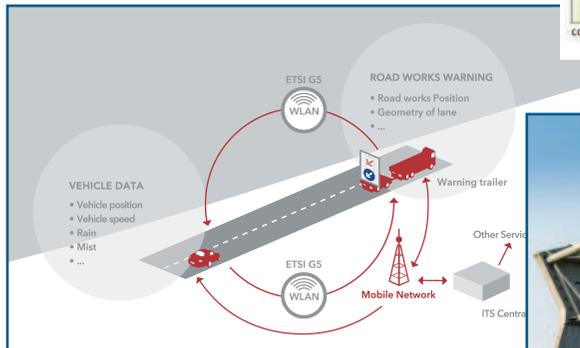
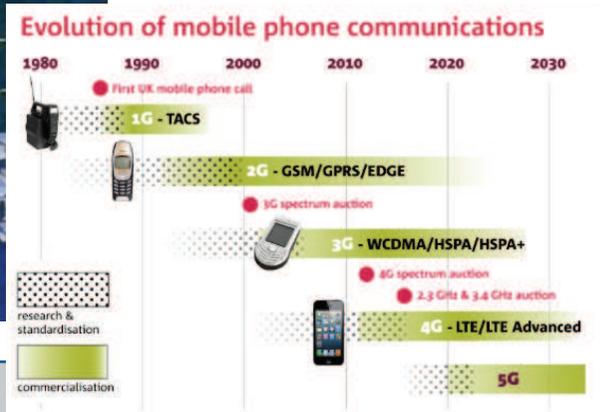




1987











# Gartner's hype cycle for emerging technologies

**2005 - 2015**

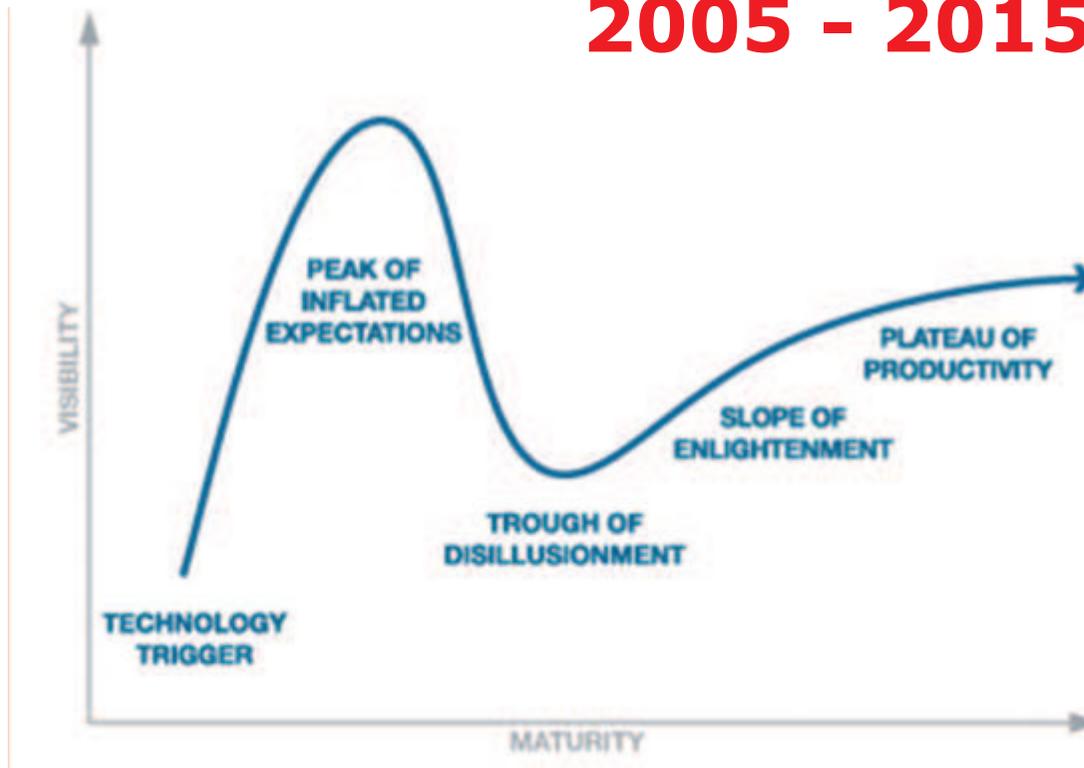
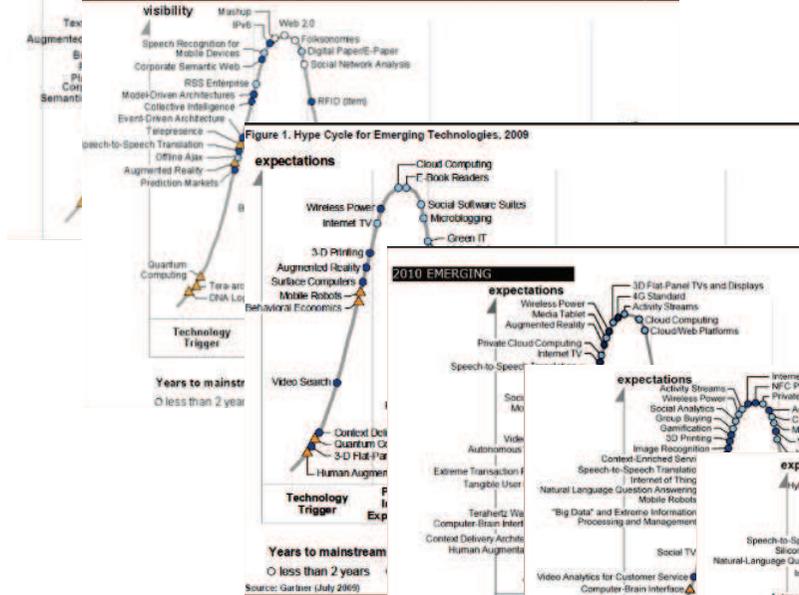


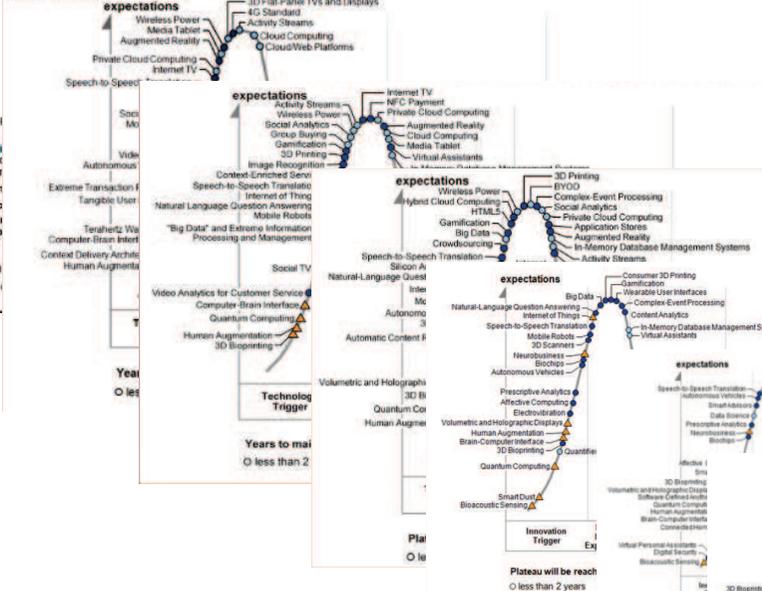


Figure 1. Hype Cycle for Emerging Technologies, 2009

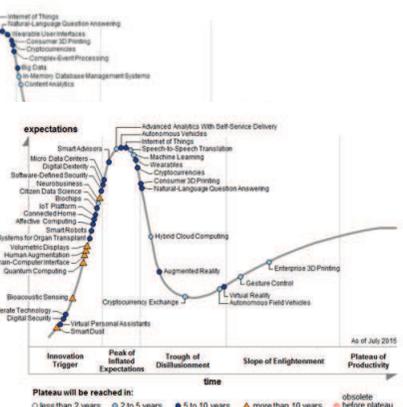


Source: Gartner (July 2009)

2010 EMERGING



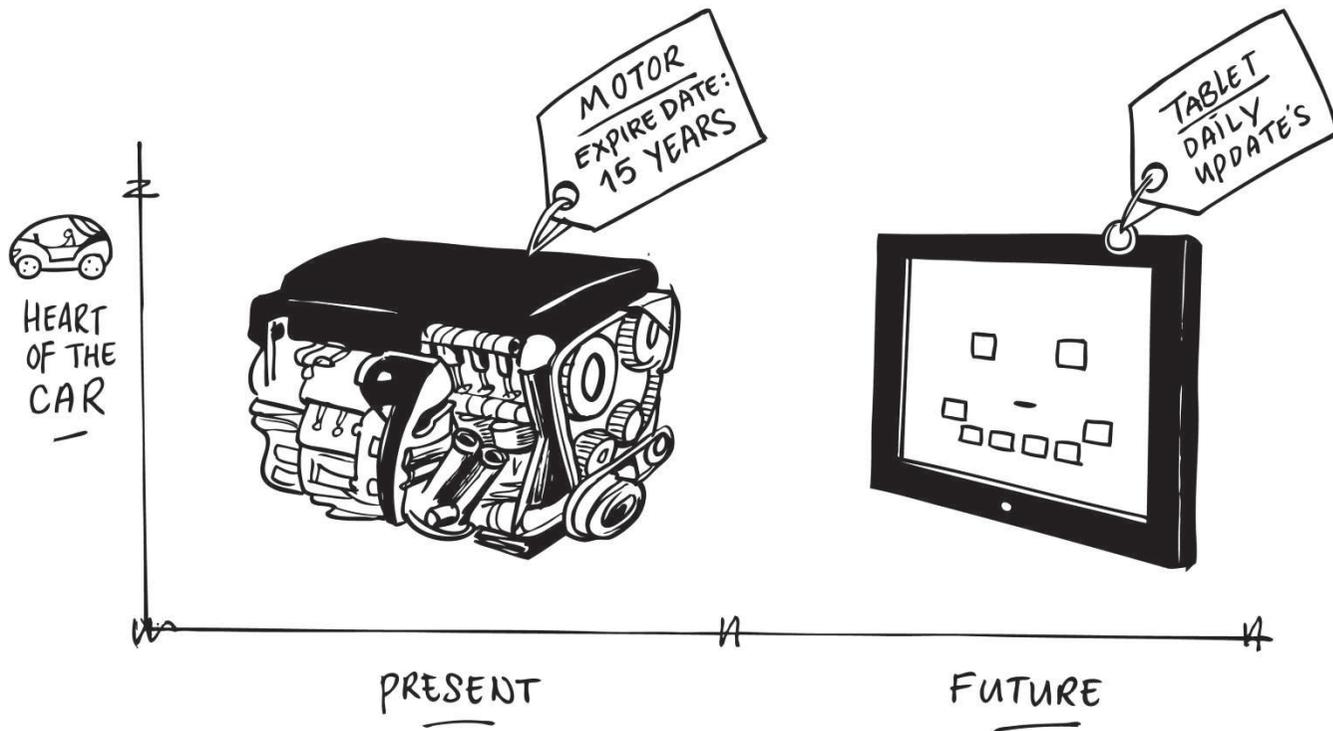
Source: Gartner August 2013



Source: Gartner (August 2015)

Source: Gartner (August 2015)

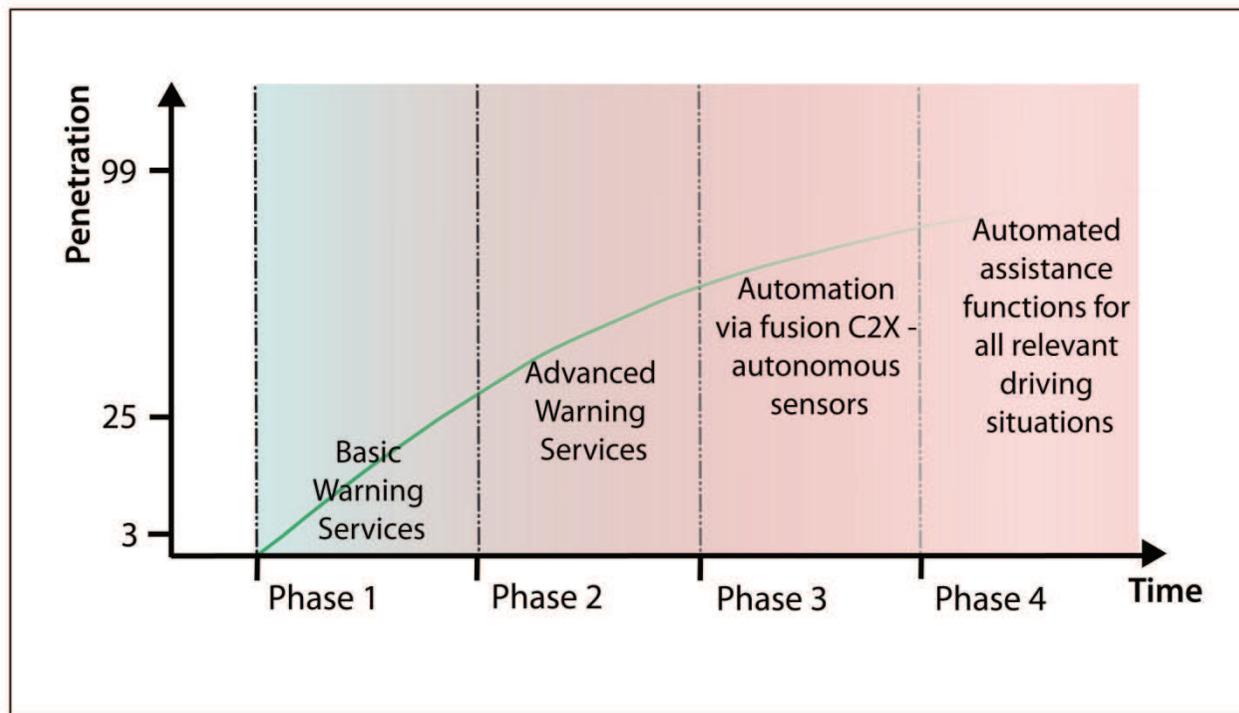






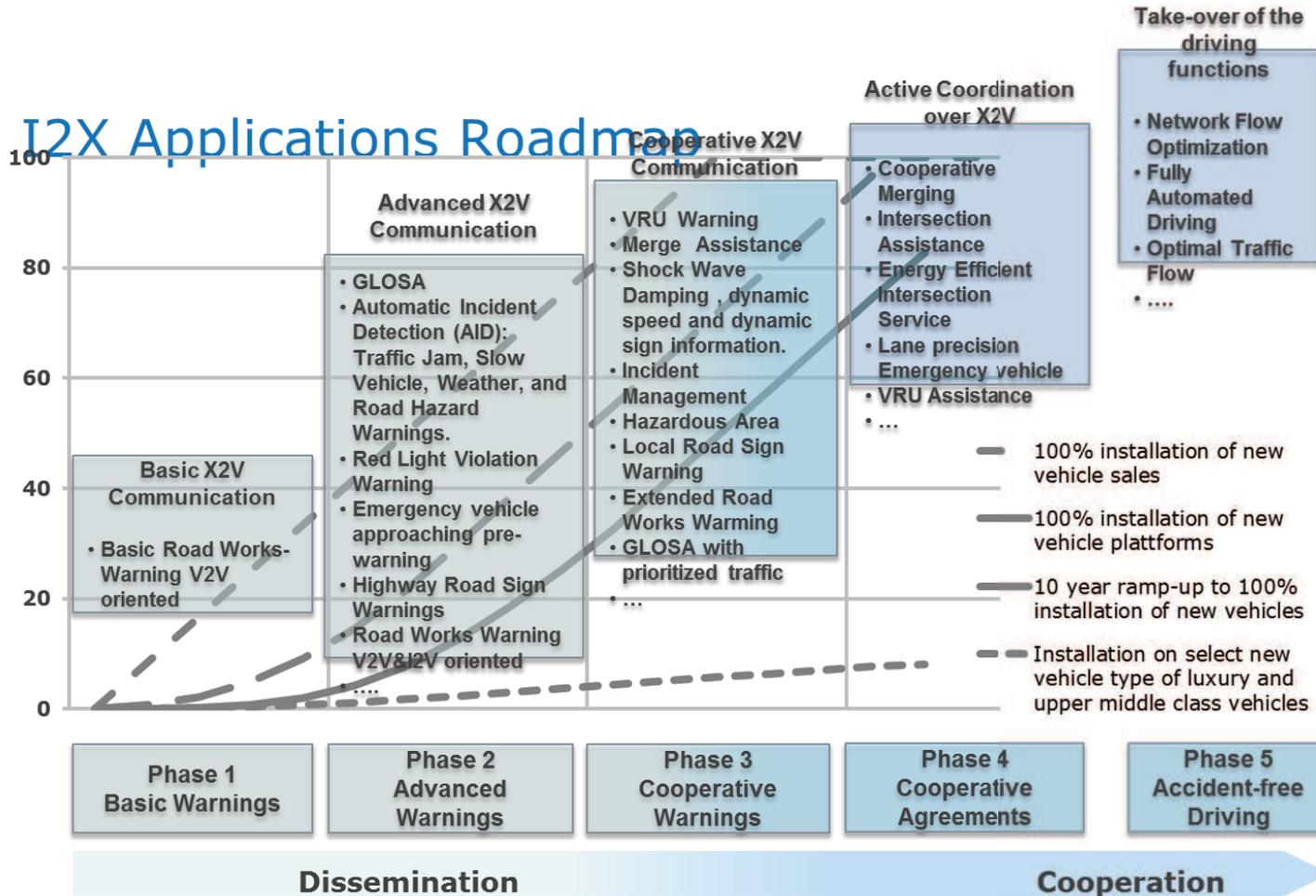
# Automotive industry development cycles

Introduction of automotive systems is linked to platform developments of 5..7 years





# Current discussions with Car2Car in AmsterdamGroup



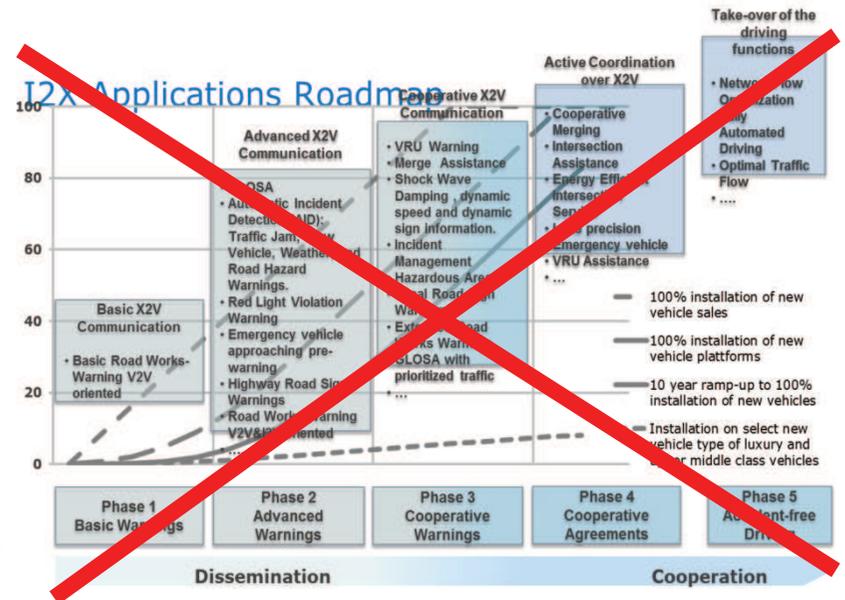


# Tesla: This Is Our Most Significant Step Towards Safe Self-Driving Cars

First it tackled highways, now it's driverless parking.

Tesla's most significant step towards safe autonomous cars is driverless parking technology it introduced last month.

.....  
Tesla introduced Summon in January in its **7.1 software update**.  
Summon is a new feature in Tesla's hands-free driving technology called autopilot.





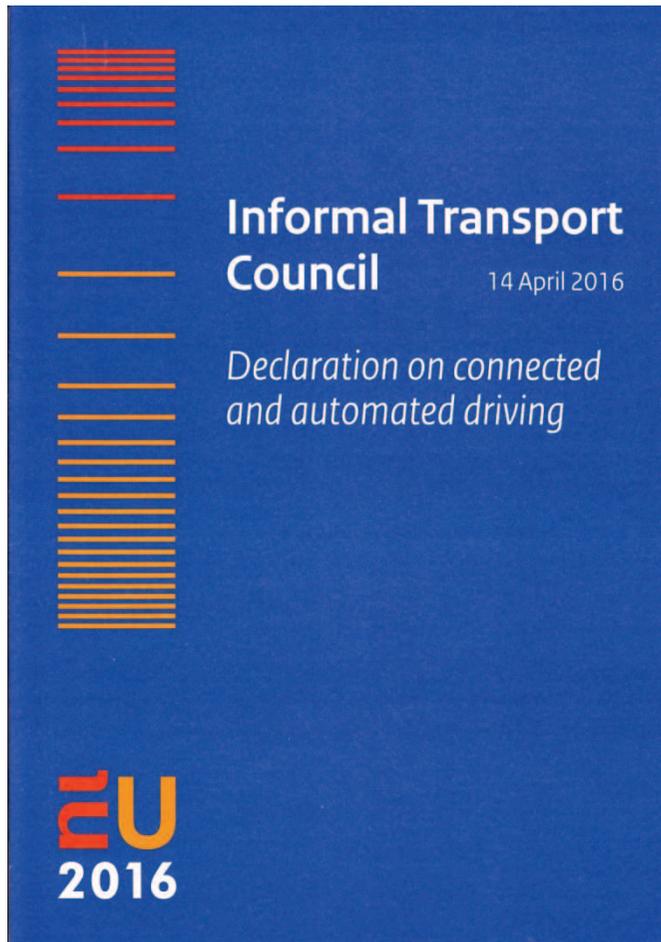
Legislation is hampering development and deployment

**‘Every driver shall at all times be able to control his vehicle or to guide his animals’**





# Declaration on connected and automated driving

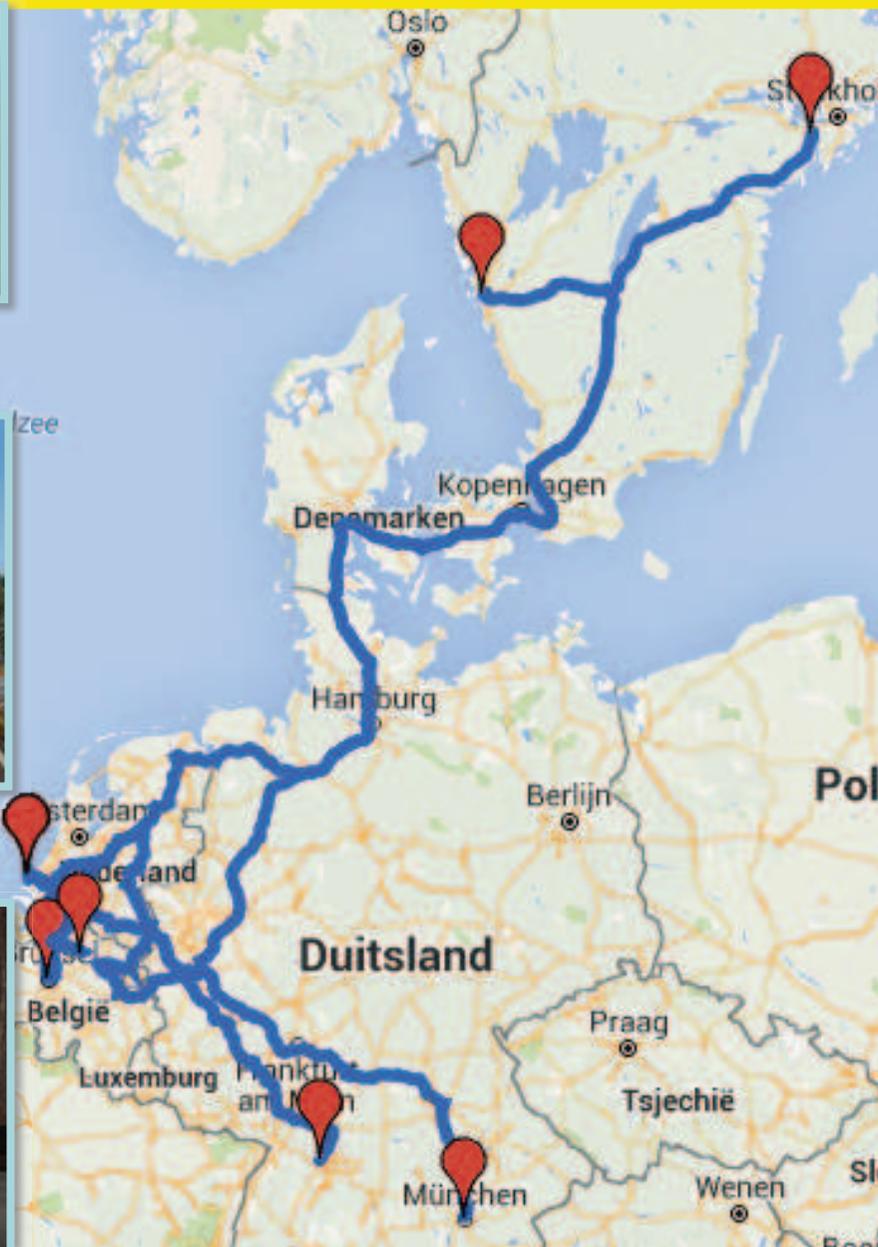


- Coherent international, European and national rules
- Use of data
- Ensure privacy, data protection and Security
- Public awareness and acceptance
- Vehicle-to-vehicle (V2V) and vehicle-to-infrastructure (V2I) communication (hybrid comm.)
- Common definitions of connected and automated driving
- International cooperation

# Truck platooning



# Challenge

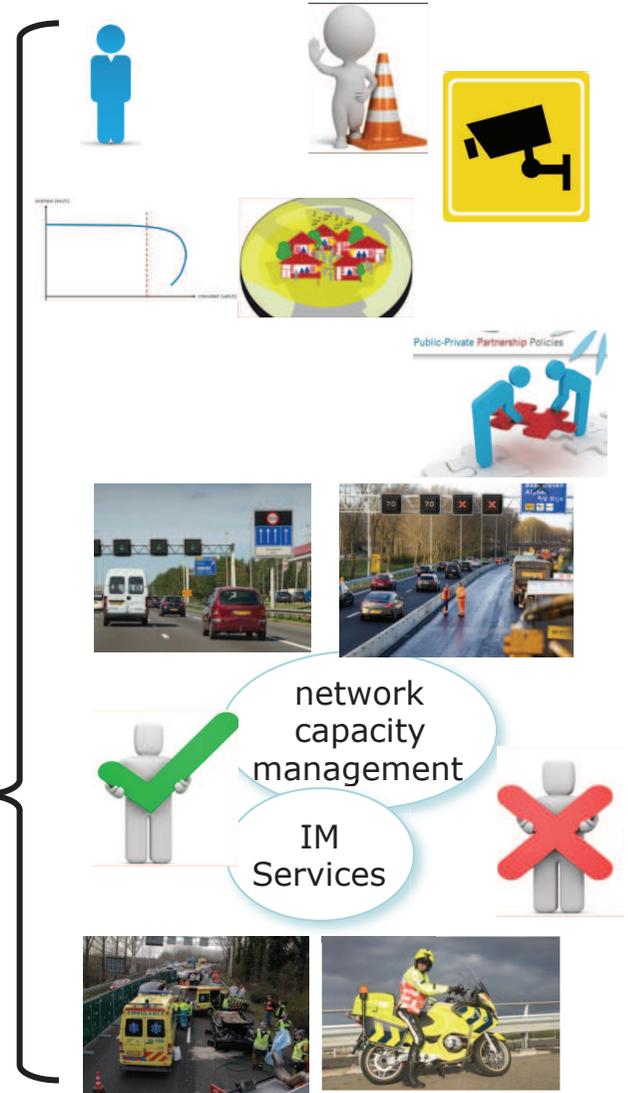


# Traffic management and Influencing factors



# Future Traffic management

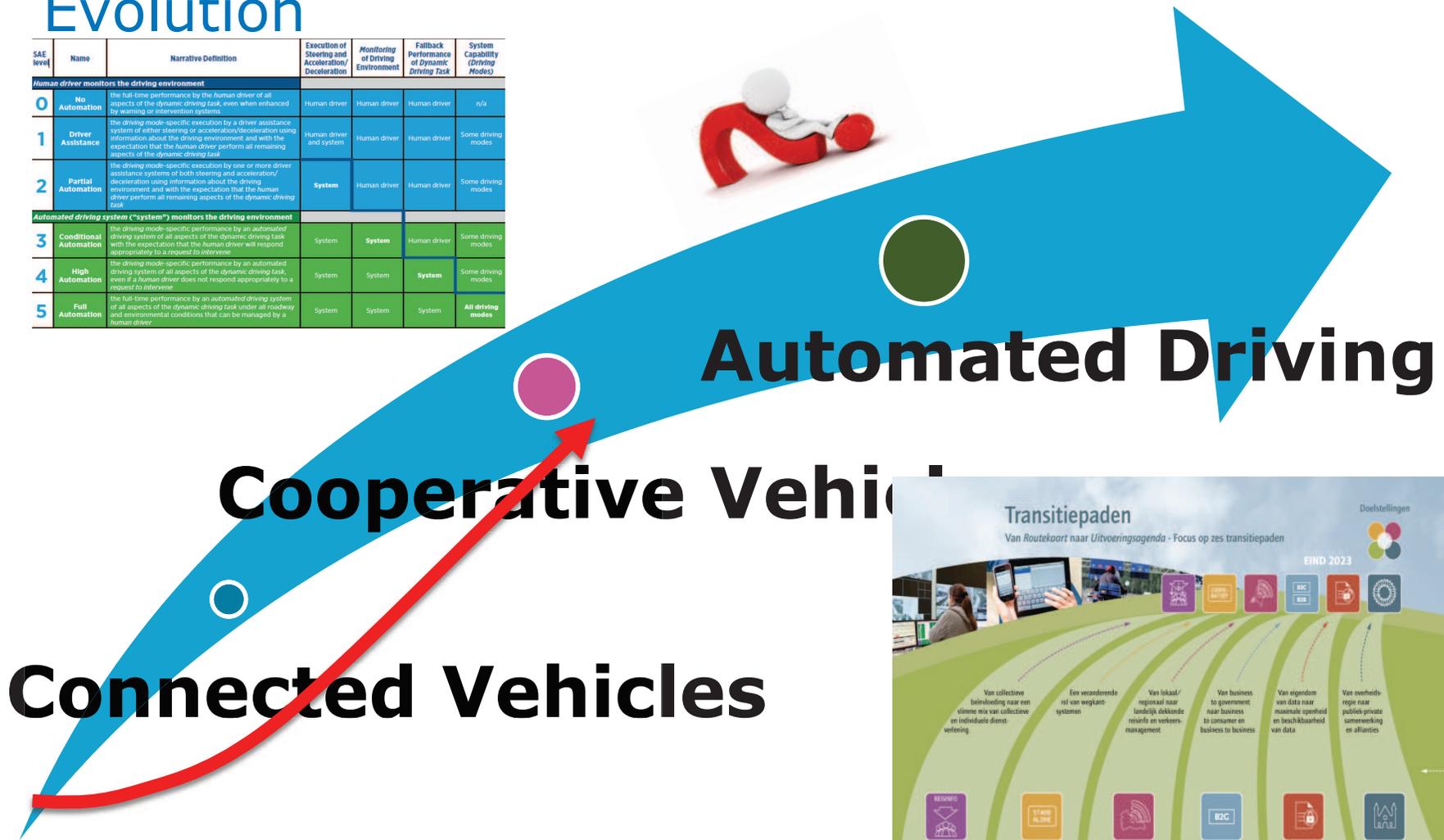
## Transition in Trafficmanagement





# Evolution

| SAE level   | Name                   | Narrative Definition  | Execution of Steering and Acceleration/Deceleration | Monitoring of Driving Environment | Fallback Performance of Dynamic Driving Task | System Capability (Driving Modes) |
|---|------------------------|---|---|-----------------------------------|--|-----------------------------------|
| <b>Human driver monitors the driving environment</b>                        |                        |   |   |                                   |  |                                   |
| 0   | No Automation          | The full-time performance by the human driver of all aspects of the dynamic driving task, even when enhanced by warning or intervention systems.  | Human driver  | Human driver                      | Human driver                                 | n/a                               |
| 1   | Driver Assistance      | The driving mode-specific execution by a driver assistance system of either steering or acceleration/deceleration using information about the driving environment and with the expectation that the human driver perform all remaining aspects of the dynamic driving task.           | Human driver and system                             | Human driver                      | Human driver                                 | Some driving modes                |
| 2   | Partial Automation     | The driving mode-specific execution by one or more driver assistance systems of both steering and acceleration/deceleration using information about the driving environment and with the expectation that the human driver perform all remaining aspects of the dynamic driving task. | System  | Human driver                      | Human driver                                 | Some driving modes                |
| <b>Automated driving system ("system") monitors the driving environment</b> |                        |   |   |                                   |  |                                   |
| 3   | Conditional Automation | The driving mode-specific performance by an automated driving system of all aspects of the dynamic driving task with the expectation that the human driver will respond appropriately to a request to intervene.  | System  | System                            | Human driver                                 | Some driving modes                |
| 4   | High Automation        | The driving mode-specific performance by an automated driving system of all aspects of the dynamic driving task, even if a human driver does not respond appropriately to a request to intervene.   | System  | System                            | System                                       | Some driving modes                |
| 5   | Full Automation        | The full-time performance by an automated driving system of all aspects of the dynamic driving task under all roadway and environmental conditions that can be managed by a human driver.   | System  | System                            | System                                       | All driving modes                 |





# Declaration on connected and automated driving

**Informal Transport Council**  
14 April 2016

*Declaration on connected and automated driving*

**EU 2016**

The diagram on the cover is divided into two main sections: "Informatization of traffic" and "Automation of the vehicle".

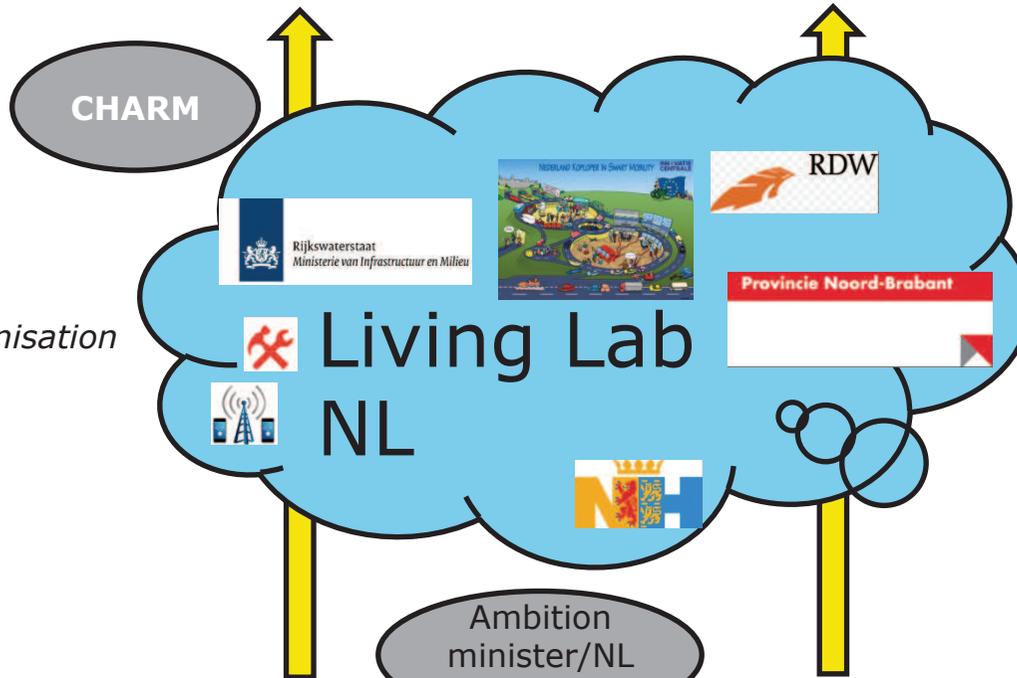
- Informatization of traffic:** A horizontal flow of yellow arrows showing the progression from "static navigation" to "real-time navigation", "speed advice", "lane guidance", and "headway advice".
- Automation of the vehicle:** A horizontal flow of orange arrows showing the progression from "driver assistance" to "partial automation", "conditional automation", "high automation", and "full automation".
- Intermediate stages:** A dashed line separates the two sections. Below it, three yellow arrows labeled "Connected", "Cooperative", and "Automated" represent the integration of the two processes.

- a coherent European framework for the deployment of interoperable connected and automated driving, which should be available, if possible, by 2019;
- bring together developments of connected and automated driving;
- adopt a "learning by experience" approach, including, where possible, cross-border cooperation, sharing and expanding knowledge and to develop practical guidelines to ensure interoperability of systems and services;

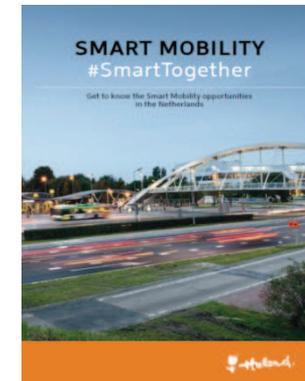


# Learning by Experience: Netherlands Testland – coherence of things

*Projects*



*National  
Strategy & Harmonisation*



*International  
cooperation*



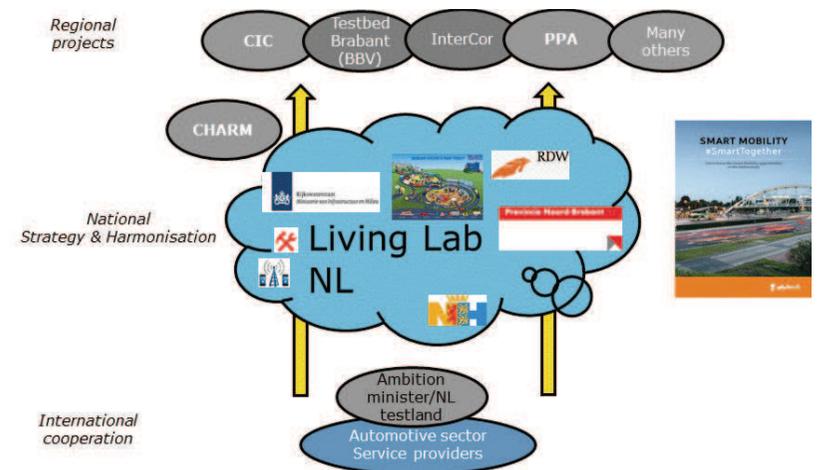
# C-ITS Corridor & INTERCOR





# Conclude:

- Learning by doing





## Conclude:

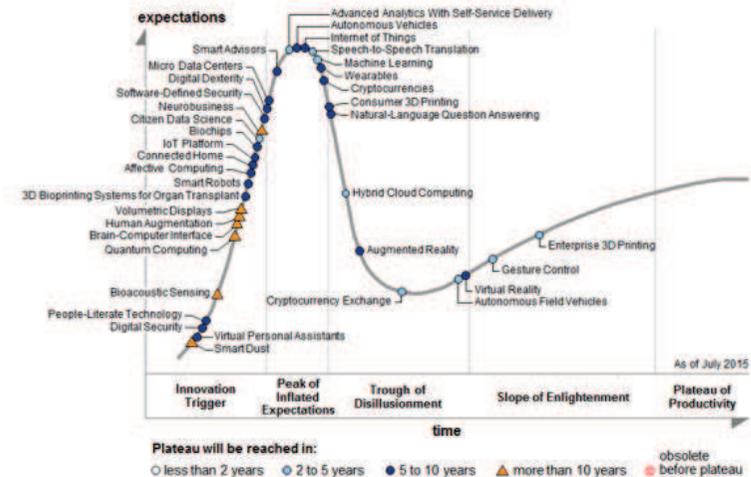
- Learning by doing
- Smart cooperation
  - (inter)national





# Conclude:

- Learning by doing
- Smart cooperation
  - (inter)national
- Adaptive & speed



Source: Gartner (August 2015)



## Conclude:

- Learning by doing
- Smart cooperation
  - (inter)national
- Adaptive & speed
- Transition TM





## Conclude:

- Learning by doing
- Smart cooperation
  - (inter)national
- Adaptive & speed
- Transition TM
- Transition paths



# Transitiepaden

Van *Werken* naar *Pensionering* - Focus op zes transitiepaden

Doelstellingen



Van MTM (makkelijk te managen) naar OBU (opa bij uitstek)

Van klushuis naar droomwoning

Van werktijd naar vrije tijd

Van dienstreizen naar vakantiereizen

Van werkbureau naar keukentafel

Van netwerkmanagement naar pretwerkmanagement



START 2016