



Rijkswaterstaat
Ministerie van Infrastructuur en Milieu

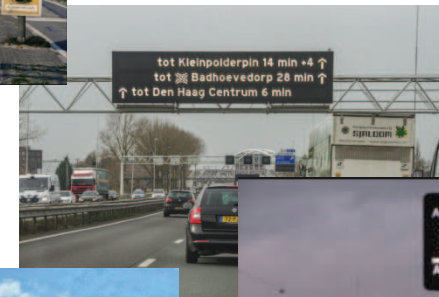


Past, Present & Future

Frans op de Beek
Principal advisor trafficmanagement
Rijkswaterstaat

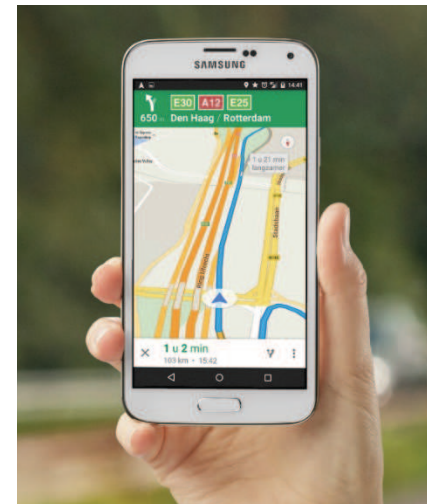


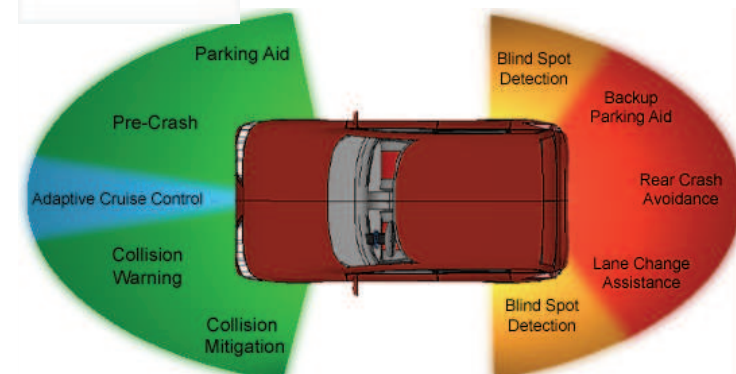
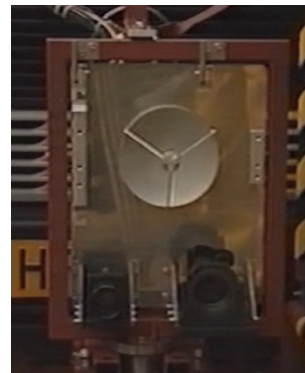
First traffic jam in NL 29-05-1955

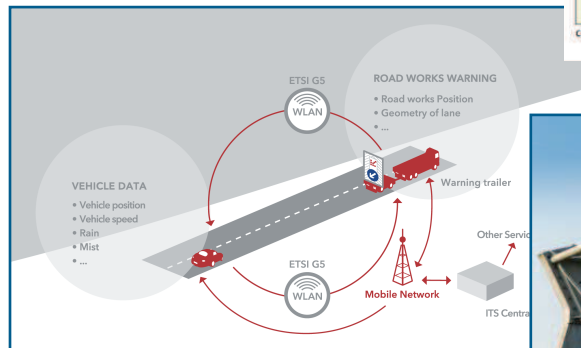
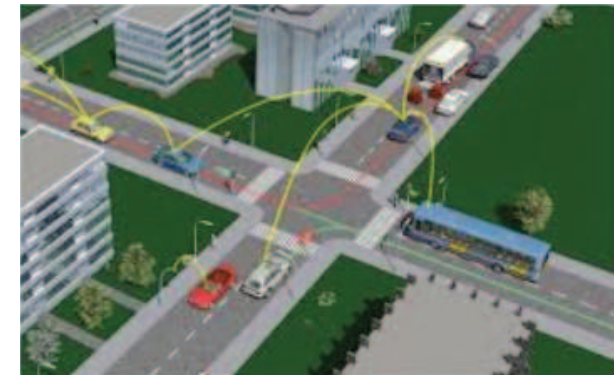
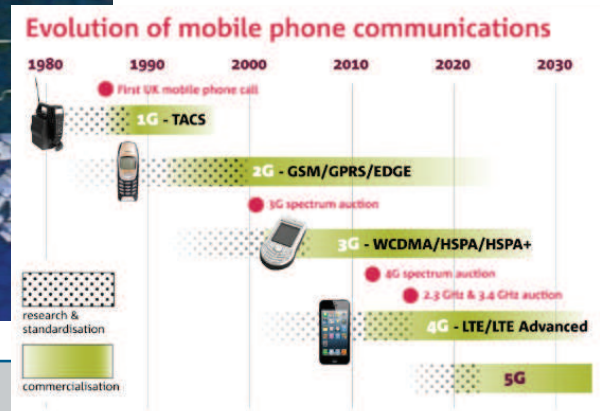




1987











Gartner's hype cycle for emerging technologies

2005 - 2015

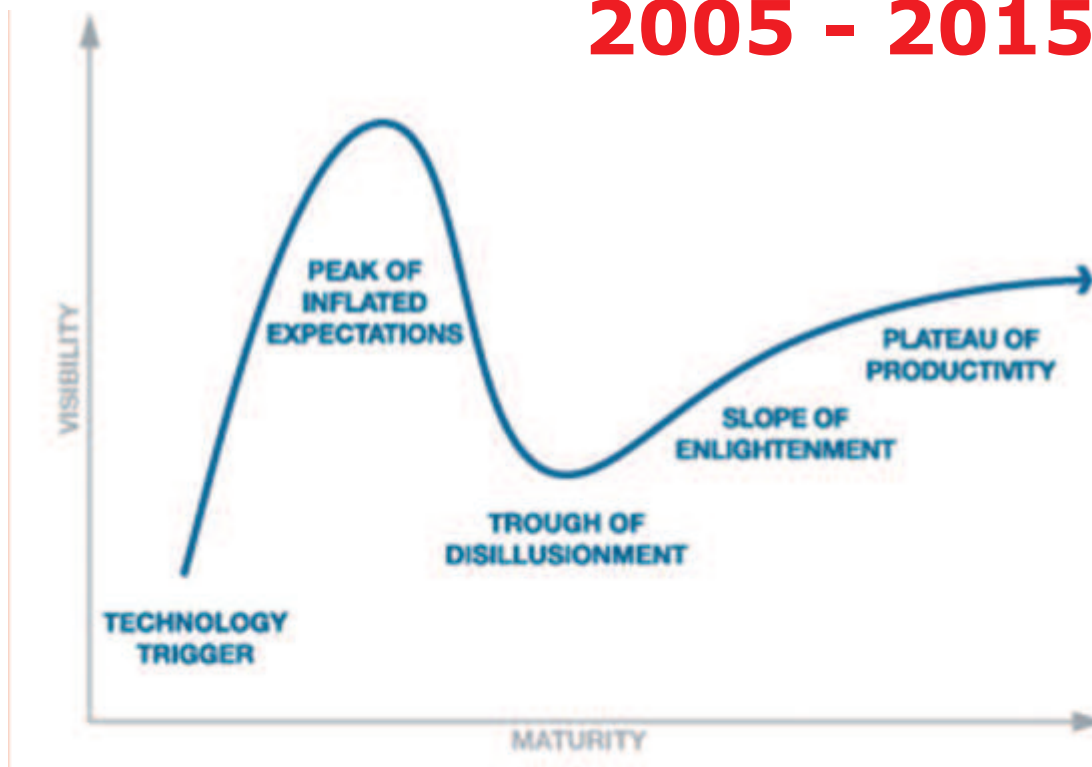
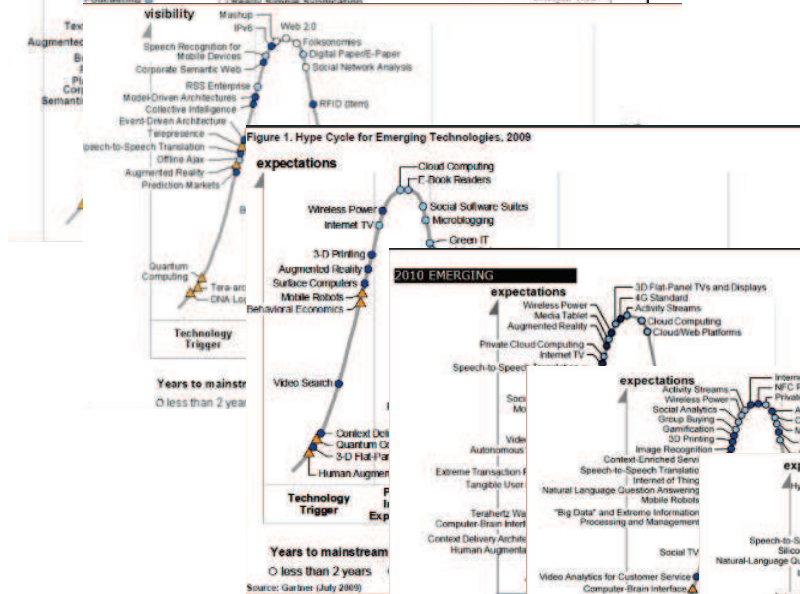




Figure 1. Hype Cycle for Emerging Technologies, 2008

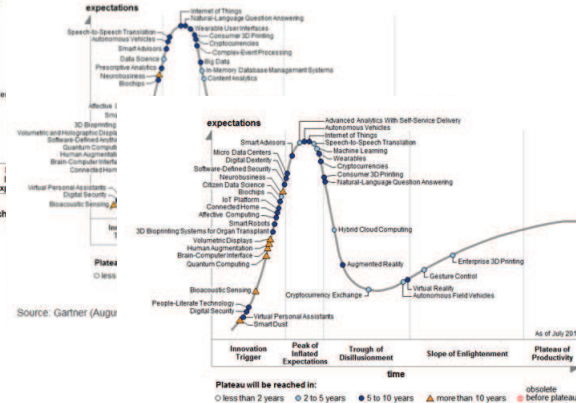


Source: Gartner (July 2009)

2010 EMERGING



Source: Gartner August 2013



Source: Gartner (August 2015)



Source: Gartner (August 2015)

Evolution of Computer Power/Cost

MIPS per \$1000 (1997 Dollars)

Million

1000

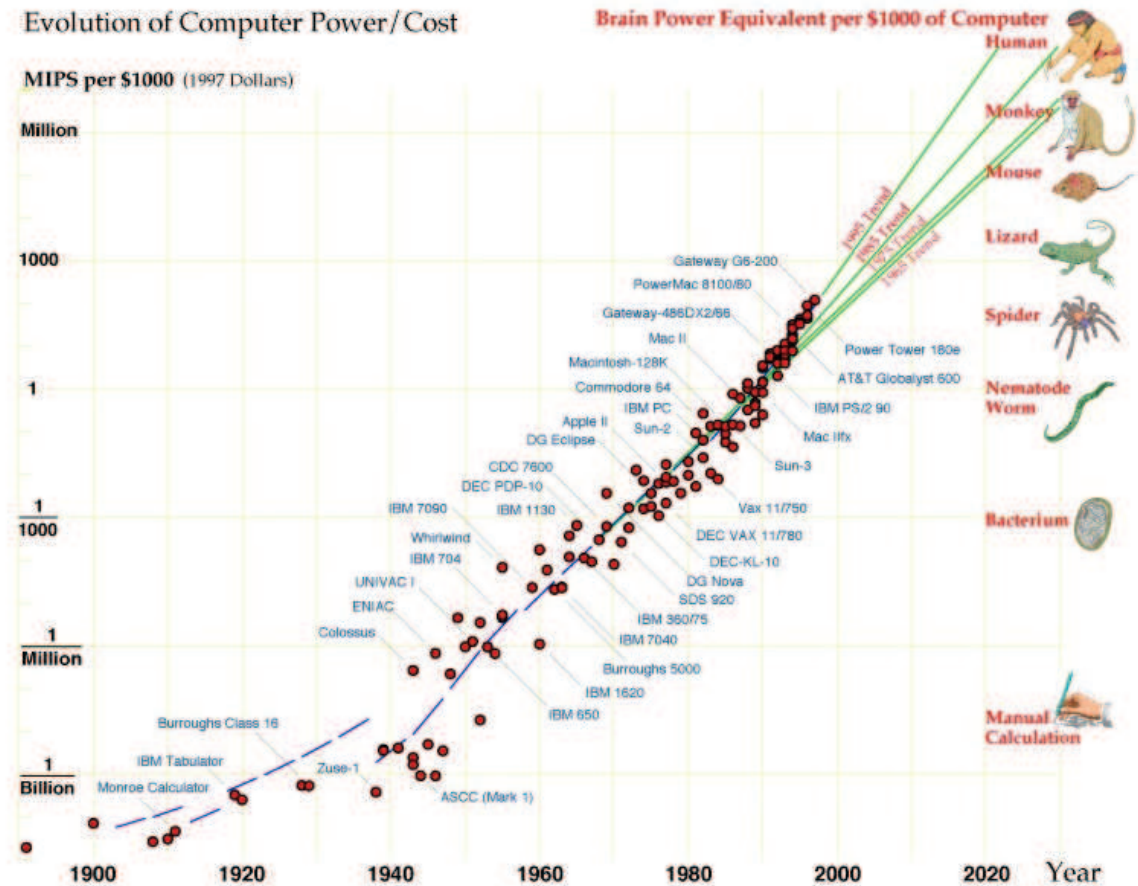
1

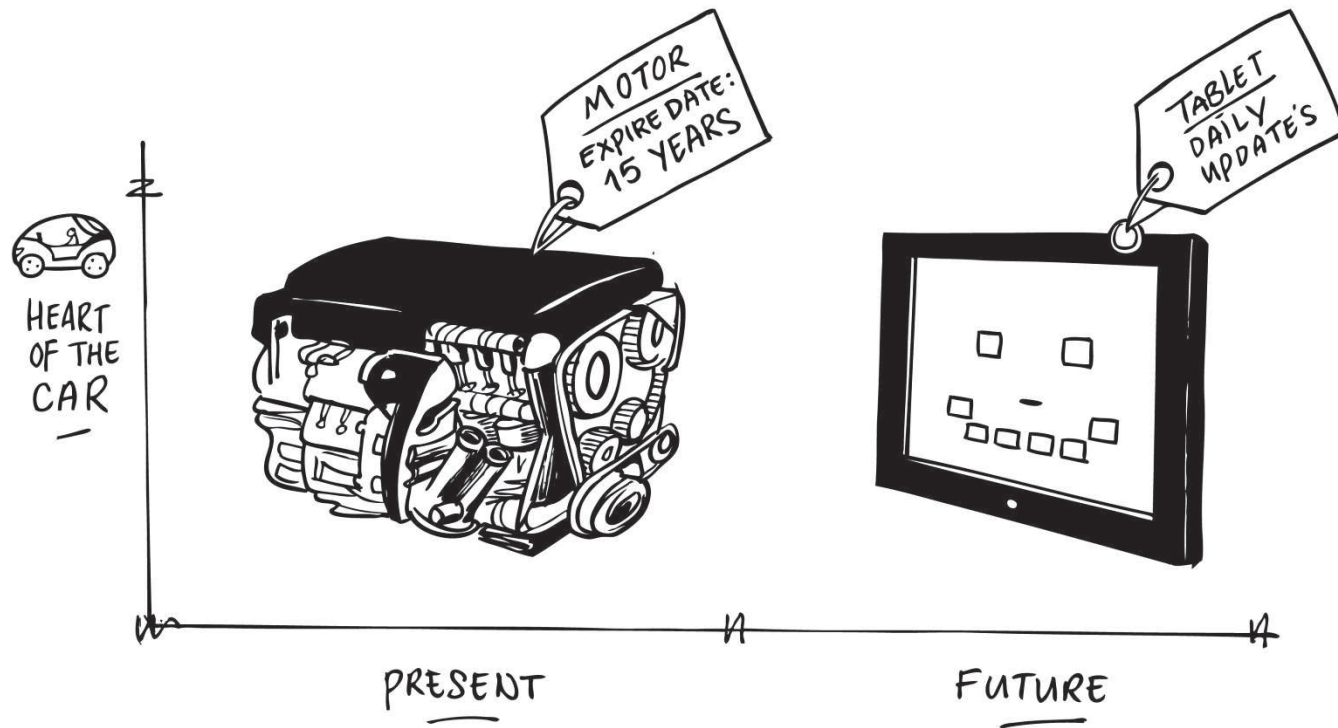
1/1000

1 Million

1 Billion

Year

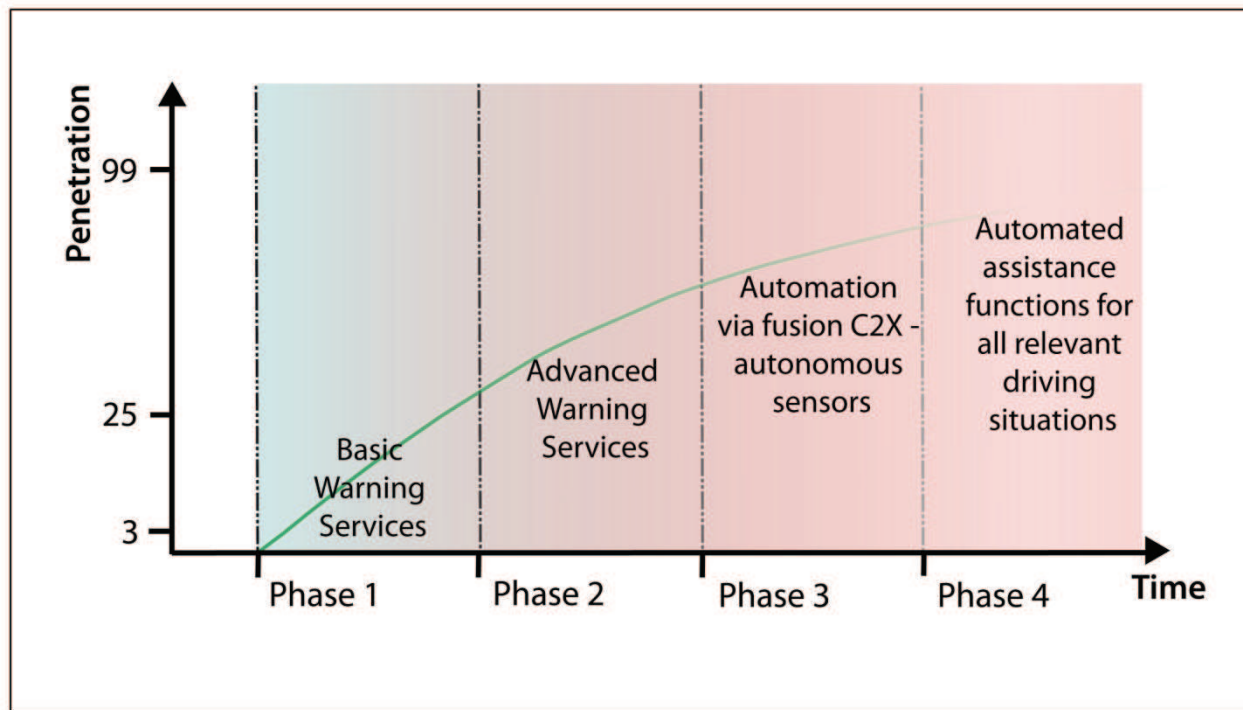






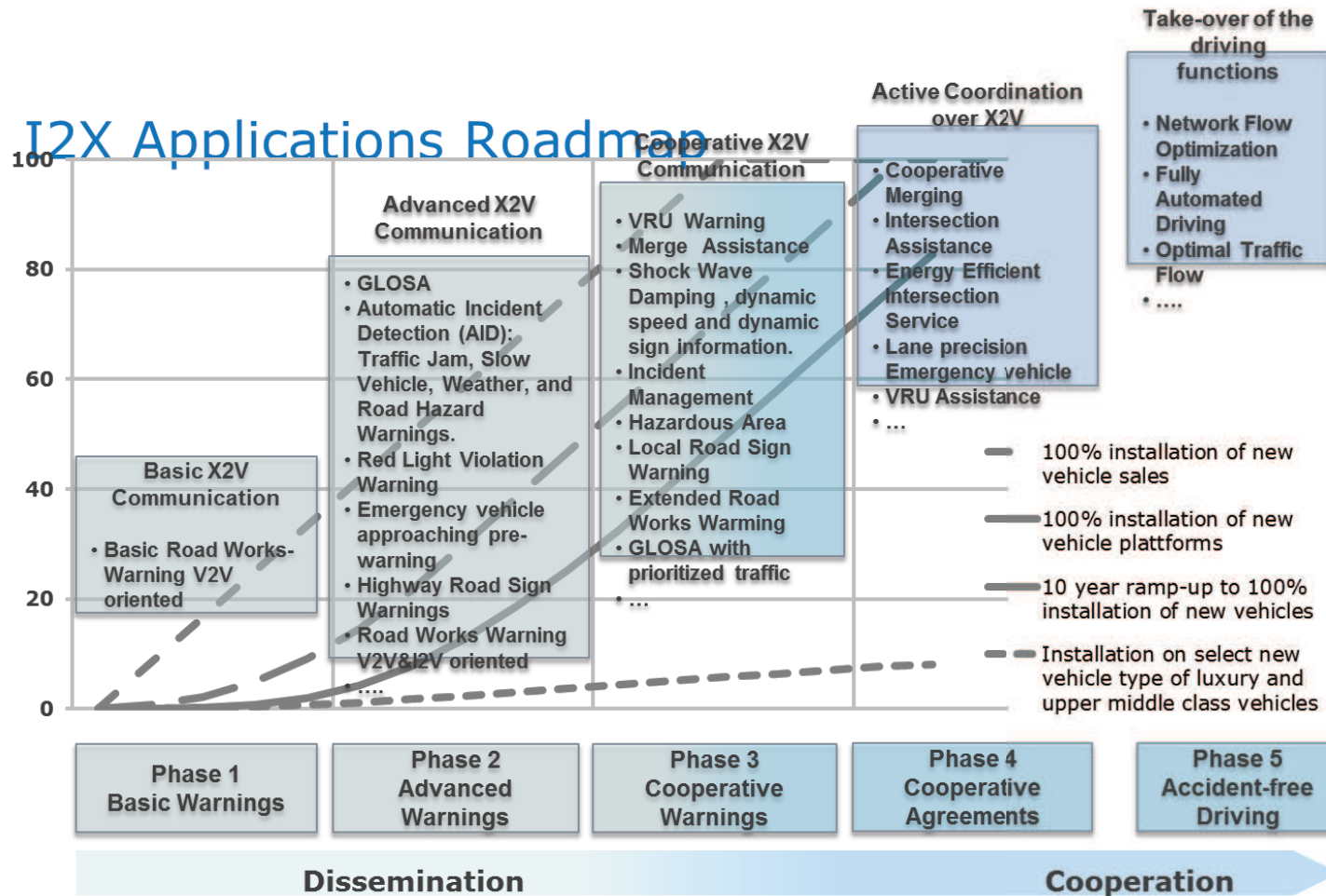
Automotive industry development cycles

Introduction of automotive systems is linked to platform developments of 5..7 years





Current discussions with Car2Car in AmsterdamGroup



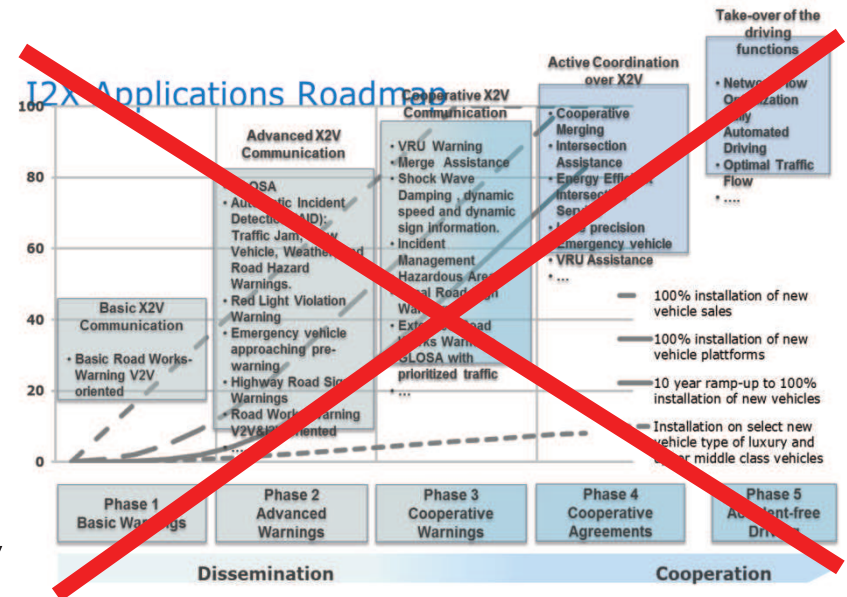


Tesla: This Is Our Most Significant Step Towards Safe Self-Driving Cars

First it tackled highways, now it's driverless parking.

Tesla's most significant step towards safe autonomous cars is driverless parking technology it introduced last month.

.....
Tesla introduced Summon in January in its **7.1 software update**.
Summon is a new feature in Tesla's hands-free driving technology called autopilot.





Legislation is hampering development and deployment

‘Every driver shall at all times be able to control his vehicle or to guide his animals’





Declaration on connected and automated driving

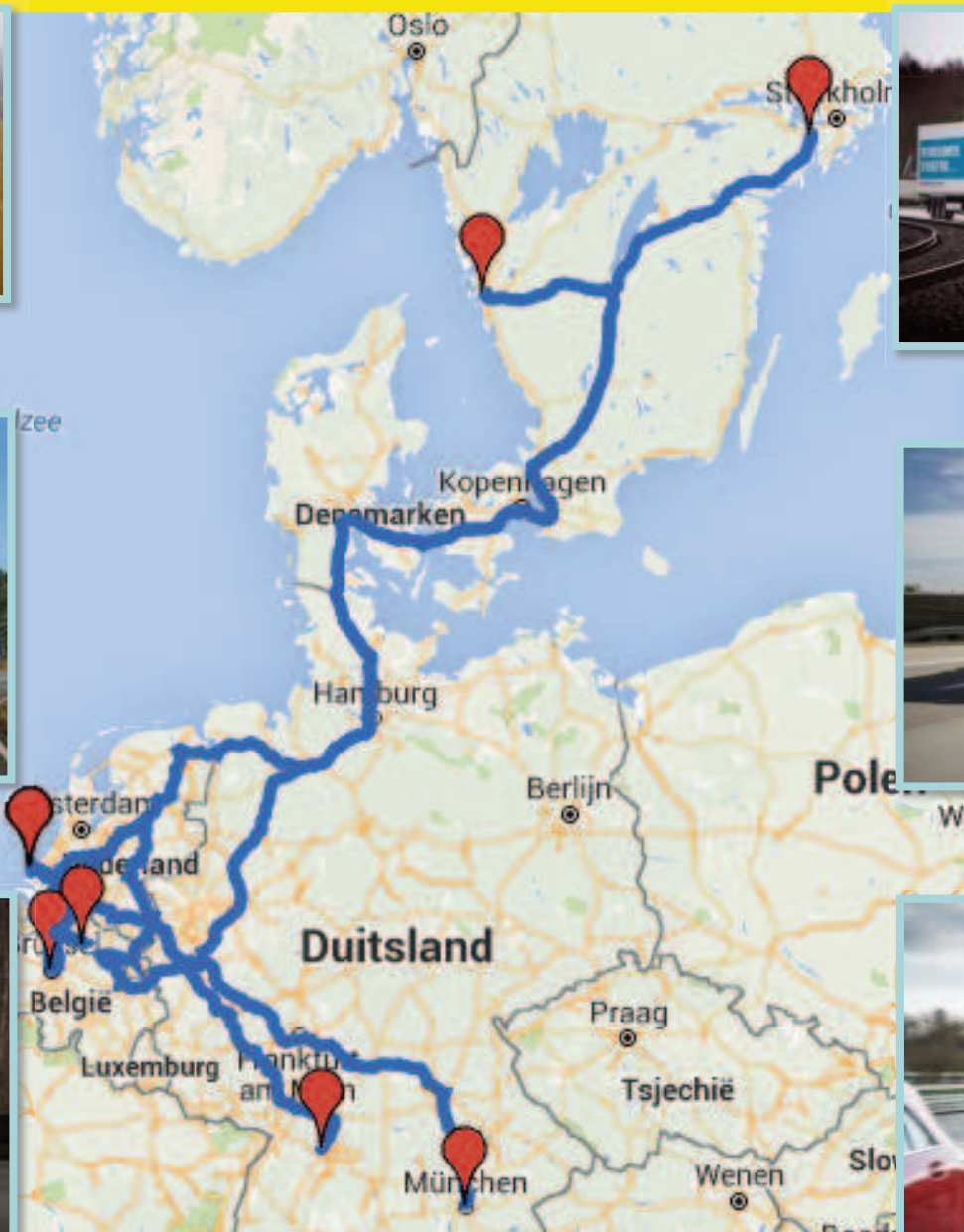


- Coherent international, European and national rules
- Use of data
- Ensure privacy, data protection and Security
- Public awareness and acceptance
- Vehicle-to-vehicle (V2V) and vehicle-to-infrastructure (V2I) communication (hybrid comm.)
- Common definitions of connected and automated driving
- International cooperation

Truck platooning



Challenge

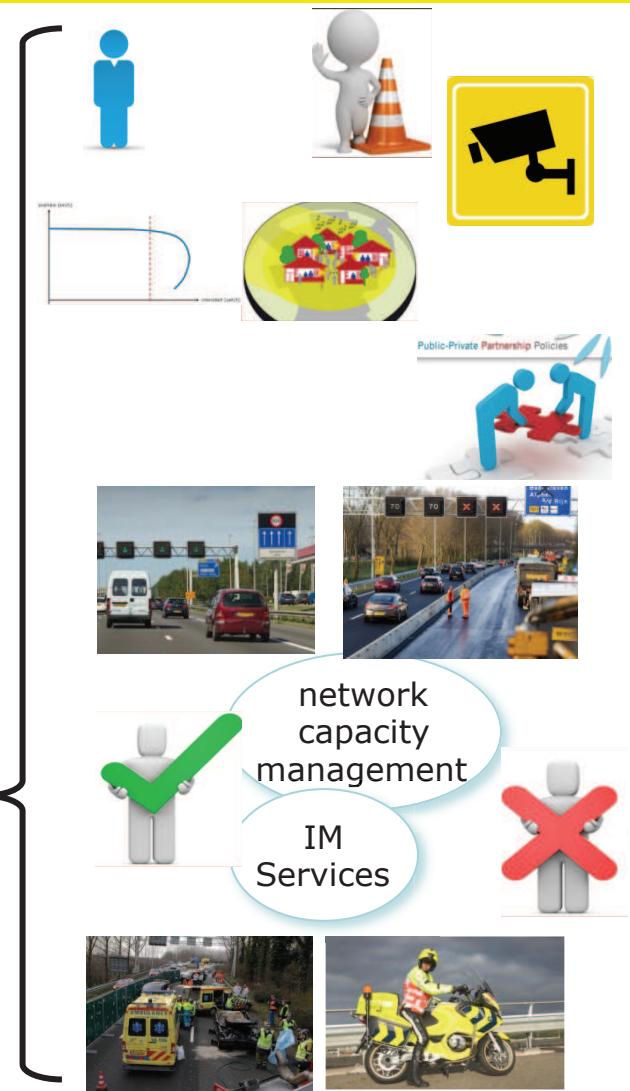


Traffic management and Influencing factors



Future Traffic management

Transition in Trafficmanagement





Evolution

SAE level	Name	Narrative Definition	Execution of Steering and Acceleration/Deceleration	Monitoring of Driving Environment	Fallback Performance of Dynamic Driving Task	System Capability (Driving Modes)
Human driver monitors the driving environment						
0	No Automation	the full-time performance by the human driver of all aspects of the dynamic driving task, even when enhanced by warning or intervention systems.	Human driver	Human driver	Human driver	n/a
1	Driver Assistance	the driving mode-specific execution by a driver assistance system of either steering or acceleration/deceleration using information about the driving environment and with the expectation that the human driver perform all remaining aspects of the dynamic driving task.	Human driver and system	Human driver	Human driver	Some driving modes
2	Partial Automation	the driving mode-specific execution by one or more driver assistance systems of both steering and acceleration/deceleration using information about the driving environment and with the expectation that the human driver perform all remaining aspects of the dynamic driving task.	System	Human driver	Human driver	Some driving modes
Automated driving system ("system") monitors the driving environment						
3	Conditional Automation	the driving mode-specific performance by an automated driving system of all aspects of the dynamic driving task with the expectation that the human driver will respond appropriately to a request to intervene.	System	System	Human driver	Some driving modes
4	High Automation	the driving mode-specific performance by an automated driving system of all aspects of the dynamic driving task, even if a human driver does not respond appropriately to a request to intervene.	System	System	System	Some driving modes
5	Full Automation	the full-time performance by an automated driving system of all aspects of the dynamic driving task under all roadway and environmental conditions that can be managed by a human driver.	System	System	System	All driving modes

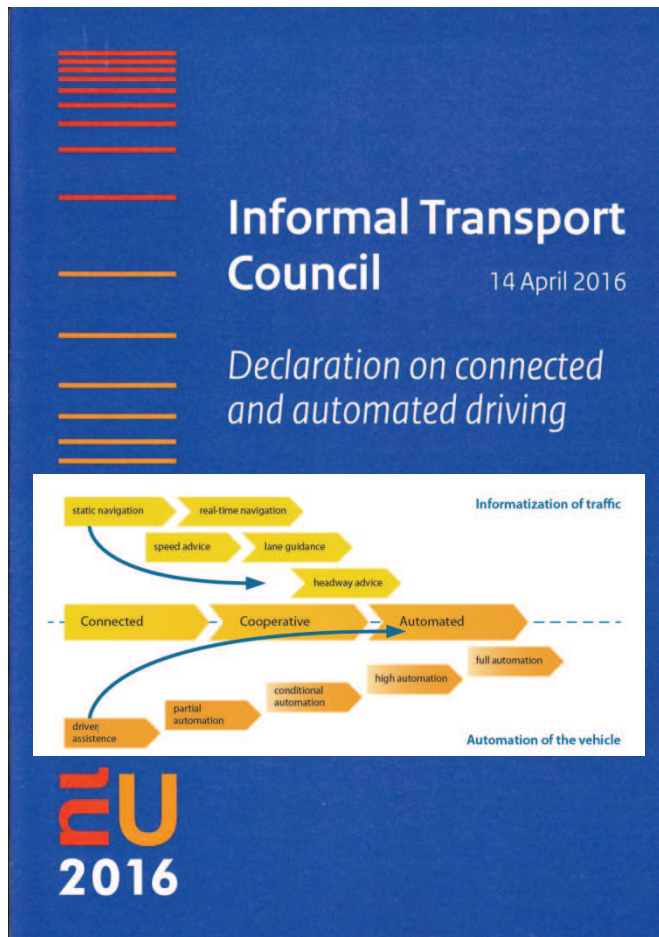


Automated Driving
Cooperative Vehicle
Connected Vehicles





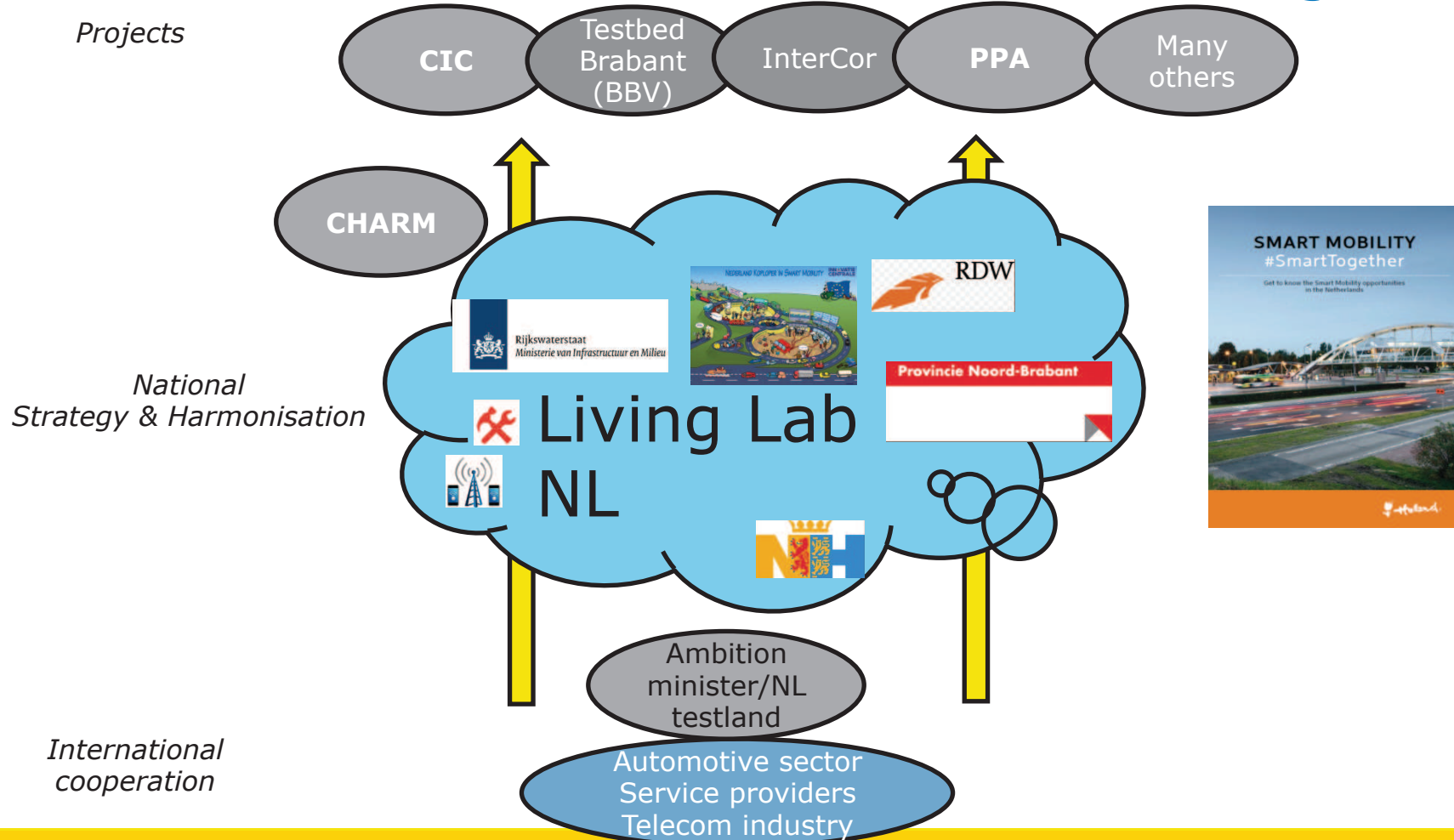
Declaration on connected and automated driving



- a coherent European framework for the deployment of interoperable connected and automated driving, which should be available, if possible, by 2019;
- bring together developments of connected and automated driving;
- adopt a "learning by experience" approach, including, where possible, cross-border cooperation, sharing and expanding knowledge and to develop practical guidelines to ensure interoperability of systems and services;



Learning by Experience: Netherlands Testland – coherence of things



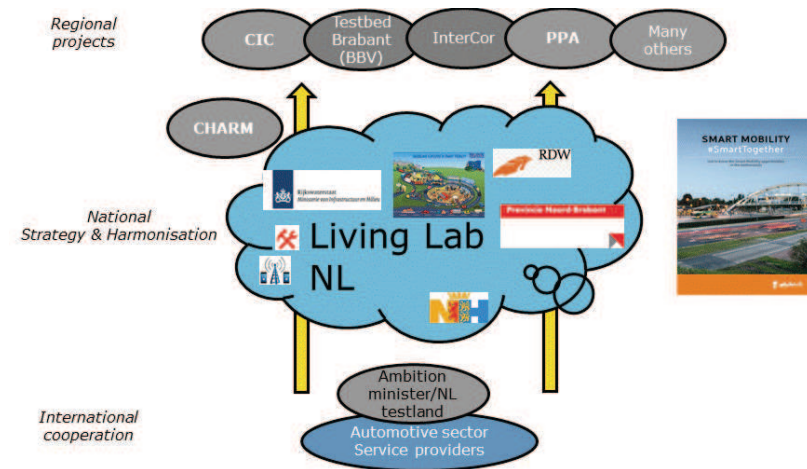
C-ITS Corridor & INTERCOR





Conclude:

- Learning by doing





Conclude:

- Learning by doing
- Smart cooperation
 - (inter)national





Conclude:

- Learning by doing
- Smart cooperation
 - (inter)national
- Adaptive & speed



Source: Gartner (August 2015)



Conclude:

- Learning by doing
- Smart cooperation
 - (inter)national
- Adaptive & speed
- Transition TM





Conclude:

- Learning by doing
- Smart cooperation
 - (inter)national
- Adaptive & speed
- Transition TM
- Transition paths



Transitiepaden

Van *Werken* naar *Pensionering* - Focus op zes transitiepaden

Doelstellingen



Van MTM (makkelijk te managen) naar OBU (opa bij uitstek)

Van klushuis naar droomwoning

Van werktijd naar vrije tijd

Van dienstreizen naar vakantiehuizen

Van werkbureau naar keukentafel

Van netwerkmanagement naar pretwerkmanagement



START 2016